

Servo motors EMME-AS

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Servo motors EMME-AS

Key features

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Everything from a single source

Motors EMME-AS

→ 3



- Brushless, permanently excited synchronous servo motors
- Reliable, dynamic, precise
- Choice of feedback systems:
 - Digital single-turn absolute displacement encoder
 - Digital multi-turn absolute displacement encoder
- Optimised connection technology

- Winding variants
 - For single-phase motor controller
 - For three-phase motor controller
 - Speed-optimised
- Protection class: IP21 (motor shaft)
- Protection class: IP65 (motor housing and connection technology)

- Optional:
 - Holding brake

Gear units EMGA-EAS/-SAS

→ 15



- Low-backlash planetary gear unit
- Gear ratio $i = 3$ and 5, available ex-stock
- Life-time lubrication
- Protection class: IP54

- Other gear unit types, ratios, designs and versions on request

Motor controllers CMM-AS

→ Internet: cmm



- Digital servo controller (0.5 kVA ... 12 kVA)
- Actuation of AC servo and linear motors
- Integrated EMC filters
- Integrated brake chopper
- Integrated safety functions

- Position controller with closed-loop position control (256 position sets)
- Speed controller
- Torque control via current controller
- Range of control functions

- Interfaces:
 - I/O interface
 - CANopen, standard
 - PROFIBUS DP, optional module
 - DeviceNet, optional module
 - PROFINET RT, optional module
 - EtherCAT, optional module
 - EtherNet/IP, optional module

Motor and encoder cables NEBM

→ 17



- Suitable for use with energy chains
- Connection technology on motor side with protection to IP65
- Can be used in a wide temperature range

Axial and parallel kits EAMM

→ Internet: eamm



- Defined kits for all electromechanical axes from Festo

- Each kit includes the relevant necessary coupling housing, couplings and motor flange as well as all screws

- Optionally with protection to IP65

PROFIBUS®, PROFINET®, DeviceNet®, CANopen®, EtherCAT®, EtherNet/IP® is a registered trademark of its respective trademark holder in certain countries.

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Type codes

EMME – AS – 60 – S – LS – AM

Type	
EMME	Motor

Motor type	
AS	Servo motor

Motor flange size	
40	40 mm
60	60 mm
80	80 mm
100	100 mm

Length	
S	Short
M	Medium

Winding	
LS	Low-voltage, standard
LV	Low-voltage, speed-optimised
HS	High-voltage, standard

Electrical connection	
A	Angled plug, fixed – outlet direction: shaft

Measuring unit	
S	Absolute encoder, single-turn
M	Absolute encoder, multi-turn

Brake	
–	None
B	With brake

Servo motors EMME-AS

Technical data

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Technical data

Flange size	40	
Length	S	M
Winding	LV	LV
Motor		
Nominal voltage	[V DC]	360
Nominal current	[A]	0.7
Continuous current at standstill	[A]	0.8
Peak current	[A]	3.2
Rated output	[W]	110
Nominal torque	[Nm]	0.12
Peak torque	[Nm]	0.7
Torque at standstill	[Nm]	0.18
Nominal rotational speed	[rpm]	9,000
Max. rotational speed	[rpm]	10,000
Motor constant	[Nm/A]	0.171
Voltage constant (phase-to-phase)	[mV/min]	13.5
Winding resistance	[Ω]	25.6
Winding inductance	[mH]	14.8
Total moment of inertia of drive output		
Without brake	[kgcm ²]	0.03
With brake	[kgcm ²]	0.055
Shaft load at nominal rotational speed		
Radial	[N]	105
Axial	[N]	21
Brake		
Operating voltage	[V DC]	24 +6 ... -10%
Output	[W]	8
Holding torque	[Nm]	0.4
Mass moment of inertia	[kgcm ²]	0.014

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Technical data

Technical data			
Flange size		60	
Length	S		M
Winding	LS		LS
Motor			
Nominal voltage	[V DC]	360	360
Nominal current	[A]	0.8	1.5
Continuous current at standstill	[A]	0.9	1.8
Peak current	[A]	3.6	7.2
Rated output	[W]	190	380
Nominal torque	[Nm]	0.6	1.2
Peak torque	[Nm]	2.8	6.0
Torque at standstill	[Nm]	0.7	1.5
Nominal rotational speed	[rpm]	3,000	3,000
Max. rotational speed	[rpm]	5,131	4,925
Motor constant	[Nm/A]	0.750	0.800
Voltage constant (phase-to-phase)	[mV/min]	49.6	51.7
Winding resistance	[Ω]	26.4	9.8
Winding inductance	[mH]	37.6	18.6
Total moment of inertia of drive output			
Without brake	[kgcm²]	0.22	0.413
With brake	[kgcm²]	0.319	0.512
Shaft load at nominal rotational speed			
Radial	[N]	250	270
Axial	[N]	50	54
Brake			
Operating voltage	[V DC]	24 +6 ... -10%	
Output	[W]	11	
Holding torque	[Nm]	2	
Mass moment of inertia	[kgcm²]	0.086	

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Technical data

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Technical data					
Flange size	80				
Length	S		M		
Winding	LS	HS	LS	HS	
Motor					
Nominal voltage	[V DC]	360	565	360	565
Nominal current	[A]	2.6	1.6	3.7	2.1
Continuous current at standstill	[A]	3.1	1.8	3.9	2.2
Peak current	[A]	12.4	7.2	15.6	8.8
Rated output	[W]	750	720	1,000	1,000
Nominal torque	[Nm]	2.4	2.3	3.2	3.2
Peak torque	[Nm]	11.2	11.2	14.0	14.0
Torque at standstill	[Nm]	2.8	2.8	3.5	3.5
Nominal rotational speed	[rpm]	3,000	3,000	3,000	3,000
Max. rotational speed	[rpm]	4,690	4,192	4,627	4,097
Motor constant	[Nm/A]	0.923	1.438	0.865	1.524
Voltage constant (phase-to-phase)	[mVmin]	54.3	95.3	55	97.5
Winding resistance	[Ω]	4.6	14.2	2.8	9.0
Winding inductance	[mH]	11.8	36.2	8.4	26.0
Total moment of inertia of drive output					
Without brake	[kgcm ²]	1.4	1.93		
With brake	[kgcm ²]	1.68	2.2		
Shaft load at nominal rotational speed					
Radial	[N]	350	360		
Axial	[N]	70	72		
Brake					
Operating voltage	[V DC]	24 +6 ... -10%		24 +6 ... -10%	
Output	[W]	12		12	
Holding torque	[Nm]	4.5		4.5	
Mass moment of inertia	[kgcm ²]	0.222		0.222	

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Technical data

Technical data		
Flange size	[V DC]	100
Length	S	M
Winding	HS	HS
Motor		
Nominal voltage	[V DC]	565
Nominal current	[A]	3.0
Continuous current at standstill	[A]	3.4
Peak current	[A]	13.6
Rated output	[W]	1,500
Nominal torque	[Nm]	4.8
Peak torque	[Nm]	22.4
Torque at standstill	[Nm]	5.6
Nominal rotational speed	[rpm]	3,000
Max. rotational speed	[rpm]	3,910
Motor constant	[Nm/A]	1.600
Voltage constant (phase-to-phase)	[mV/min]	102.2
Winding resistance	[Ω]	4.6
Winding inductance	[mH]	19.8
Total moment of inertia of drive output		
Without brake	[kgcm ²]	4.84
With brake	[kgcm ²]	5.63
Shaft load at nominal rotational speed		
Radial	[N]	650
Axial	[N]	130
Brake		
Operating voltage	[V DC]	24 +6 ... -10%
Output	[W]	18
Holding torque	[Nm]	9.0
Mass moment of inertia	[kgcm ²]	0.654

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Safety data									
Measuring unit	Absolute, single turn (SEK 34/37)				Absolute, multi-turn (SEL 34/37)				
Flange size	40	60	80	100	40	60	80	100	
Rotary position encoder									
MTTFd ¹⁾	Years	340		271					
Holding brake									
MTTF	Years	371	538	797	1037	371	538	797	1037
Switching cycles ²⁾		5 million idle actuations							

1) Fault exclusions for the mechanical encoder connection are not possible

2) Guide value for the number of switching actuations (release/application) during exclusive use as holding brake without friction work (i.e. jamming at standstill)

Technical data – Encoder													
Measuring unit	Absolute, single-turn (SEK 34/37)				Absolute, multi-turn (SEL 34/37)								
Operating voltage	[V DC]	7 ... 12 ($\pm 5\%$)											
Interface signals/protocol– HIPERFACE®													
Measuring principle	Capacitive												
Process data channel	SIN, REFSIN, COS, REF COS (analogue differential)												
Sinusoidal/cosinusoidal periods per revolution	16												
Parameter channel	RS485 (digital)												
Absolute position values per revolution	512 (resolution 9 bit)												
Maximum speed													
For absolute value generation	[1/min]	6,000											
Mechanical	[1/min]	12,000											
Revolutions		1		4,096 revolutions, 12 bits									
Interpolation of sine/cosine signals in the motor controller ¹⁾													
Measurement step at 12 bit		20" (angular seconds)											
Angular accuracy		$\pm 20'$ (angular minutes)											

1) Dependent on the motor controller.

Weight [kg]								
Flange size	40		60		80		100	
Length	S	M	S	M	S	M	S	M
Without brake	0.6	0.7	1.7	2.2	3.4	4.1	6.3	7.3
With brake	0.7	0.8	2.0	2.6	4.1	4.8	7.3	8.3

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Technical data

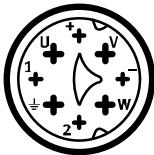
Operating and environmental conditions

Standard	IEC60034	
Protection class		
Motor shaft	IP21	
Motor shaft and connection technology	IP65	
Ambient temperature	[°C]	-10 ... +40 (up to 100 °C with derating of 1.5% per degree Celsius)
Storage temperature	[°C]	-20 ... +70
Insulation protection class		F (155 °C)
Temperature monitoring		Not integrated, only via I^2t temperature monitoring model of the motor controller
Rated class to EN 60034-1		S1 (continuous operation)
Thermal class to EN 60034-1		F (155 °C)
Relative air humidity	[%]	0 ... 90 (non-condensing)
CE marking (see declaration of conformity)		To EU Low Voltage Directive To EU EMC Directive ¹⁾
Certification		cULus Recognized (OL) RCM trademark
Note on materials		RoHS-compliant Contains PWIS (paint-wetting impairment substances)

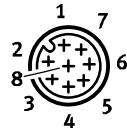
- 1) For information about the applicability of the component see the manufacturer's EC declaration of conformity at: www.festo.com/sp → User documentation.
If the component is subject to restrictions on usage in residential, office or commercial environments or small businesses, further measures to reduce the emitted interference may be necessary.

Pin allocation – Motor side

Motor (M16, pins)



Encoder (M12, pins)



Pin	Function
U	Phase U
V	Phase V
W	Phase W
PE	Protective earth (PE)
+	Brake BR+
-	Brake BR-
1	n.c.
2	n.c.

Pin	Function
1	0 V
2	Us (7 ... 12 V DC)
3	Data+ (RS485)
4	Data- (RS485)
5	SIN+
6	SIN- (REFSIN)
7	COS+
8	COS- (REFCOS)

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Technical data

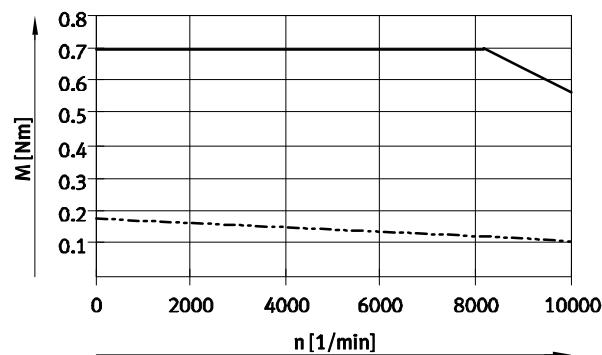
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Torque M as a function of rotational speed n

Flange size 40

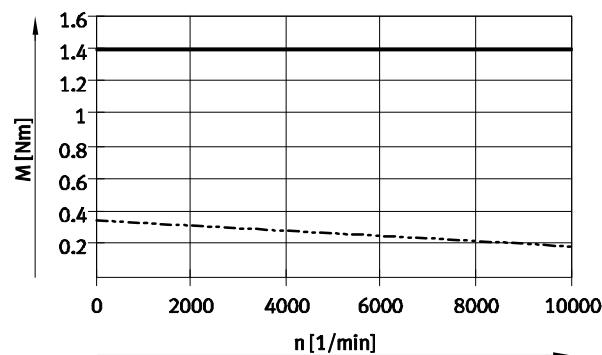
Length S

Winding LV



Length M

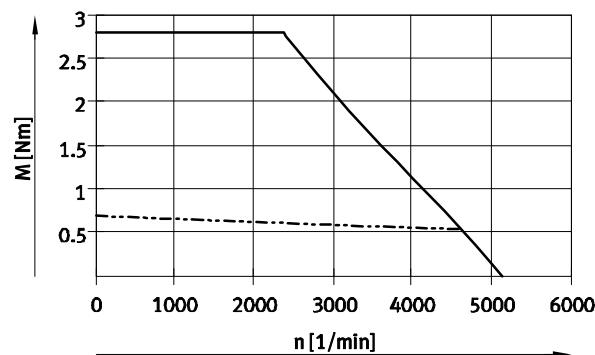
Winding LV



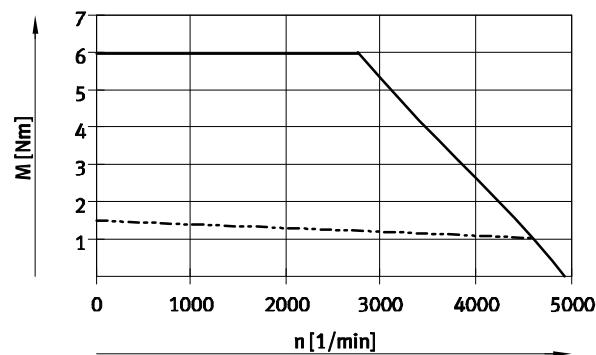
Flange size 60

Length S

Winding LS



Length M



— Peak torque
- - - Nominal torque

- - Note

Typical motor characteristic curve
with nominal voltage and optimal
controller.

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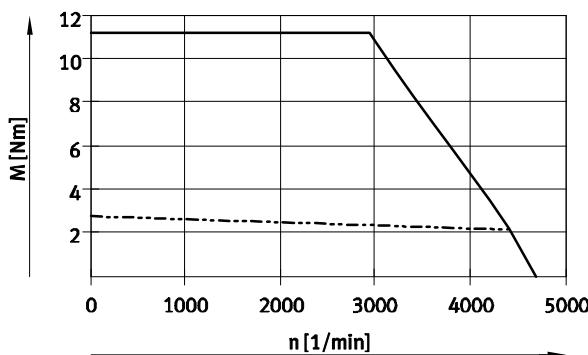
Technical data

Torque M as a function of rotational speed n

Flange size 80

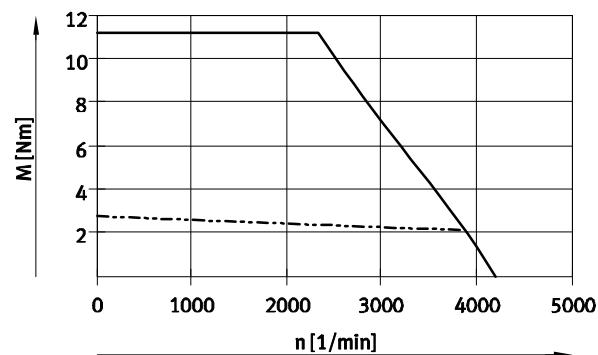
Length S

Winding LS



Length S

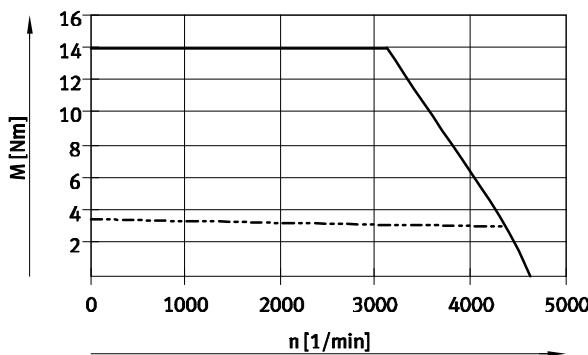
Winding HS



Flange size 80

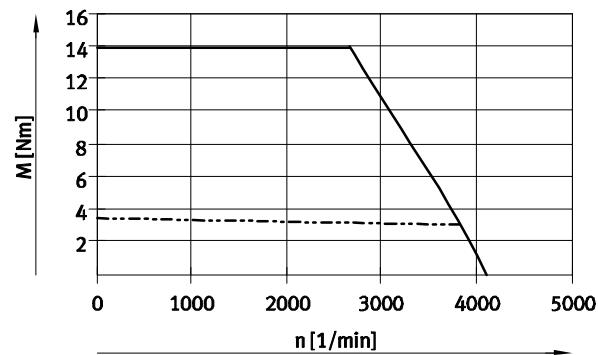
Length M

Winding LS



Length M

Winding HS



— Peak torque
- - Nominal torque

- - Note

Typical motor characteristic curve
with nominal voltage and optimal
controller.

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Technical data

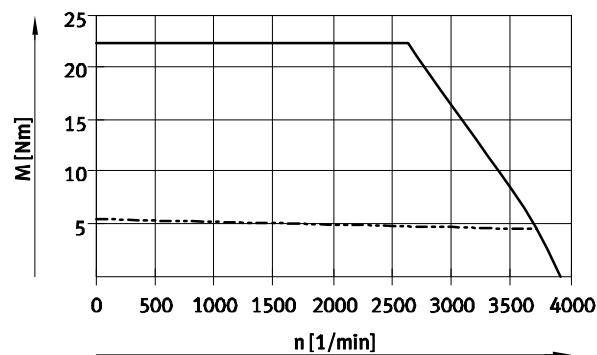
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Torque M as a function of rotational speed n

Flange size 100

Length S

Winding HS



— Peak torque

- - - Nominal torque

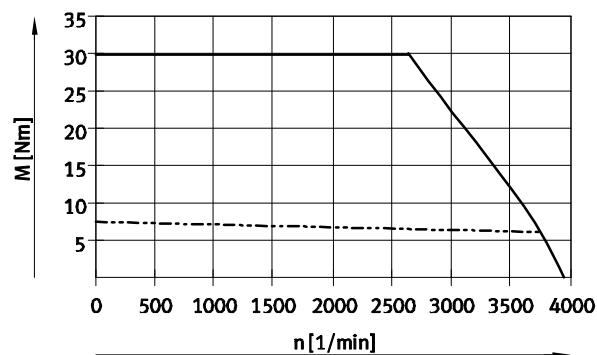


Note

Typical motor characteristic curve
with nominal voltage and optimal
controller.

Length M

Winding HS



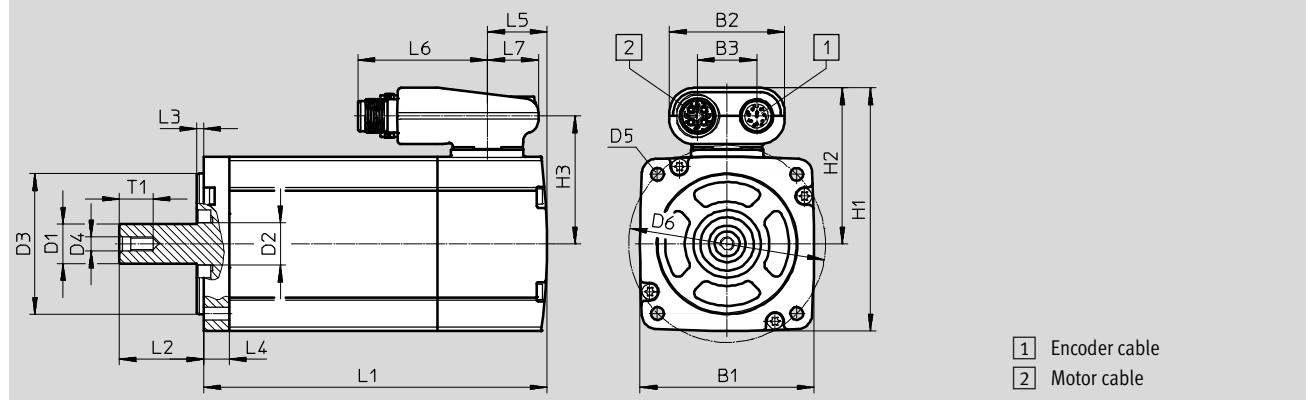
Servo motors EMME-AS

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Technical data

Dimensions

Download CAD data → www.festo.com



Flange size	Length	B1	B2	B3	D1 Ø h6	D2 Ø	D3 Ø h7	D4
40	S	40	41	21	8	10	30	M3
	M							
60	S	62	41	21	14	15	50	M5
	M							
80	S	82	41	21	19	20	70	M6
	M							
100	S	102	41	21	19	25	95	M6
	M							

Flange size	Length	D5 Ø	D6 Ø ±0.3	H1	H2	H3	L1 With brake ±2	L1 Without brake ±2
40	S	3.4	45	68.5	48.5	38.5	89	124
	M							
60	S	4.5	70	86.5	55.5	45.5	122	156
	M							
80	S	5.5	90	106.5	65.5	55.5	158	200
	M							
100	S	9	115	126.5	75.5	65.5	200	242
	M							

Flange size	Length	L2	L3	L4	L5	L6	L7	T1
			±0.2	±0.3				
40	S	20+0.5/-0.7	2.5	4.5	25.3	46.2	18	9
	M							
60	S	30+0.5/-0.2	2.5	9	21	46.2	18	12.5
	M							
80	S	35+0.4/-0.2	3	10	23	46.2	18	16
	M							
100	S	40+0.4/-0.2	3	12	25.5	46.2	18	16
	M							

Servo motors EMME-AS

Technical data

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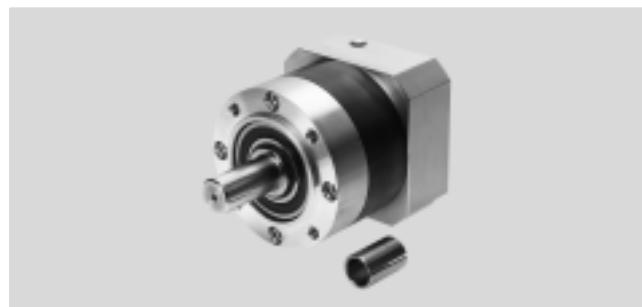
Ordering data – Stock items								Part No.	Type
Length	Winding	Measuring unit		Brake	Part No.	Type			
Short	Medium	Low-voltage, standard	Low-voltage, speed-optimised	High-voltage, standard	Encoder, single-turn	Encoder, multi-turn			
Flange size 40									
■			■		■			2082428	EMME-AS-40-S-LV-AS
■			■		■		■	2082430	EMME-AS-40-S-LV-ASB
■			■			■		2082429	EMME-AS-40-S-LV-AM
■			■			■	■	2082431	EMME-AS-40-S-LV-AMB
	■		■		■			2082444	EMME-AS-40-M-LV-AS
	■		■		■		■	2082446	EMME-AS-40-M-LV-ASB
	■		■			■		2082445	EMME-AS-40-M-LV-AM
	■		■			■	■	2082447	EMME-AS-40-M-LV-AMB
Flange size 60									
■		■			■			2089698	EMME-AS-60-S-LS-AS
■		■			■		■	2089700	EMME-AS-60-S-LS-ASB
■		■				■		2089699	EMME-AS-60-S-LS-AM
■		■				■	■	2089701	EMME-AS-60-S-LS-AMB
	■	■			■			2089730	EMME-AS-60-M-LS-AS
	■	■			■		■	2089732	EMME-AS-60-M-LS-ASB
	■	■				■		2089731	EMME-AS-60-M-LS-AM
	■	■				■	■	2089733	EMME-AS-60-M-LS-AMB
Flange size 80									
■		■			■			2093104	EMME-AS-80-S-LS-AS
■		■			■		■	2093106	EMME-AS-80-S-LS-ASB
■		■				■		2093105	EMME-AS-80-S-LS-AM
■			■			■	■	2093107	EMME-AS-80-S-LS-AMB
■				■	■			2093136	EMME-AS-80-S-HS-AS
■				■	■		■	2093138	EMME-AS-80-S-HS-ASB
■				■		■		2093137	EMME-AS-80-S-HS-AM
■				■		■	■	2093139	EMME-AS-80-S-HS-AMB
	■	■			■			2093168	EMME-AS-80-M-LS-AS
	■	■			■		■	2093170	EMME-AS-80-M-LS-ASB
	■	■				■		2093169	EMME-AS-80-M-LS-AM
	■	■				■	■	2093171	EMME-AS-80-M-LS-AMB
	■			■	■			2093200	EMME-AS-80-M-HS-AS
	■			■	■		■	2093202	EMME-AS-80-M-HS-ASB
	■			■		■		2093201	EMME-AS-80-M-HS-AM
	■			■		■	■	2093203	EMME-AS-80-M-HS-AMB
Flange size 100									
■				■	■			2103467	EMME-AS-100-S-HS-AS
■				■	■		■	2103469	EMME-AS-100-S-HS-ASB
■				■		■		2103468	EMME-AS-100-S-HS-AM
■				■		■	■	2103470	EMME-AS-100-S-HS-AMB
	■			■	■			2103499	EMME-AS-100-M-HS-AS
	■			■	■		■	2103501	EMME-AS-100-M-HS-ASB
	■			■		■		2103500	EMME-AS-100-M-HS-AM
	■			■		■	■	2103502	EMME-AS-100-M-HS-AMB

Servo motors EMME-AS

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Accessories

Gear unit EMGA



Technical data

For motor flange size	40		60		
Gear unit type	EMGA-40-P-G...-40		EMGA-60-P-G...-60		
Gear ratio [i]	3	5	3	5	
Gear unit type	Planetary gear unit				
Continuous output torque ¹⁾ [Nm]	11	14	28	40	
Max. output torque ²⁾ [Nm]	17.6	22	45	64	
Max. drive speed [rpm]	18,000		13,000		
Torsional rigidity [Nm/arcmin]	1		2.3		
Torsional backlash [deg]	0.25		0.17		
Mass moment of inertia ³⁾ [kgcm ²]	0.031	0.019	0.135	0.078	
Max. efficiency [%]	98				
Operating temperature ⁴⁾ [°C]	−25 ... +90				
Protection class	IP54				
Product weight [g]	350		900		

For motor flange size	80		100				
Gear unit type	EMGA-80-P-G...-80		EMGA-80-P-G...-100		EMGA-120-P-G...-100		
Gear ratio [i]	3	5	3	5	3		
Gear unit type	Planetary gear unit						
Continuous output torque ¹⁾ [Nm]	85	110	85	110	115		
Max. output torque ²⁾ [Nm]	136	176	136	176	184		
Max. drive speed [rpm]	7,000		7,000		6,500		
Torsional rigidity [Nm/arcmin]	6		6		12		
Torsional backlash [deg]	0.12		0.12		0.12		
Mass moment of inertia ³⁾ [kgcm ²]	0.77	0.45	0.77	0.45	2.63		
Max. efficiency [%]	98		96		96		
Operating temperature ⁴⁾ [°C]	−25 ... +90						
Protection class	IP54						
Product weight [g]	2,000		2,100		6,000		

- 1) At the output shaft
- 2) The specifications refer to an output shaft speed of 100 rpm as well as operating mode S1 and a temperature of 30 °C
- 3) Referred to the drive shaft
- 4) Note the temperature range of the motor

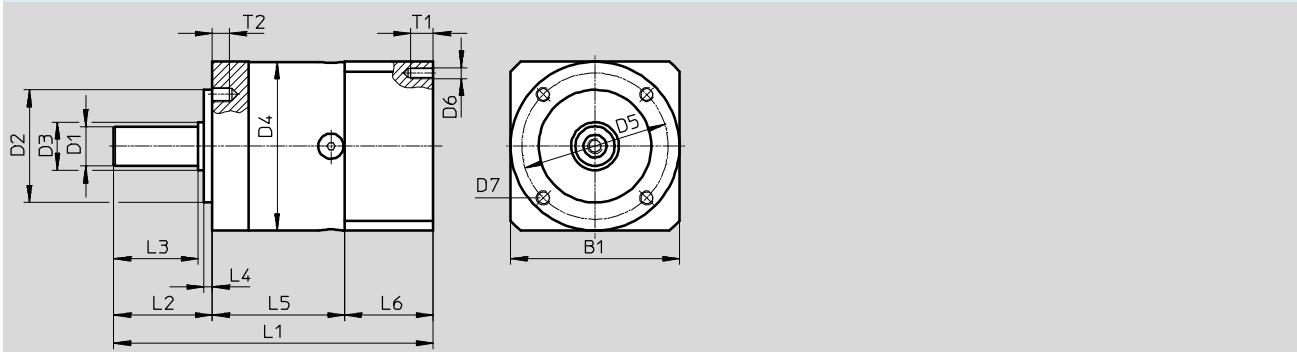
Servo motors EMME-AS

Accessories

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Dimensions

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Type	B1	D1 ∅ h7	D2 ∅ h7	D3 ∅ h7	D4 ∅	D5 ∅	D6	D7
EMGA-40-P-G...-40	40	10	26	12	40	34	M3	M4
EMGA-60-P-G...-60	60	14	40	17	60	52	M4	M5
EMGA-80-P-G...-80	80	20	60	25	80	70	M5	M6
EMGA-80-P-G...-100	100	20	60	25	80	70	M8	M6
EMGA-120-P-G...-100	115	25	80	35	115	100	M8	M10

Type	L1	L2	L3	L4	L5	L6	T1	T2
			±0.2	±0.2				
EMGA-40-P-G...-40	93.5	26	23	2	39	28.5	8	6
EMGA-60-P-G...-60	113.5	35	30	3	47	31	10	8
EMGA-80-P-G...-80	138.5	40	36	3	60	38.5	12	10
EMGA-80-P-G...-100	143.5	40	36	3	60	43.5	16	10
EMGA-120-P-G...-100	176.5	55	50	4	74	47.5	20	16

Ordering data				
For motor flange size	Gear ratio	Part No.	Type	
40	3	2297684	EMGA-40-P-G3-EAS-40	
	5	2297685	EMGA-40-P-G5-EAS-40	
60	3	2297686	EMGA-60-P-G3-EAS-60	
	5	2297687	EMGA-60-P-G5-EAS-60	
80	3	2297690	EMGA-80-P-G3-EAS-80	
	5	2297691	EMGA-80-P-G5-EAS-80	
100	3	552194	EMGA-80-P-G3-SAS-100	
	5	552195	EMGA-80-P-G5-SAS-100	
	3	552196	EMGA-120-P-G3-SAS-100	
	5	552197	EMGA-120-P-G5-SAS-100	

Servo motors EMME-AS

FESTO

Accessories

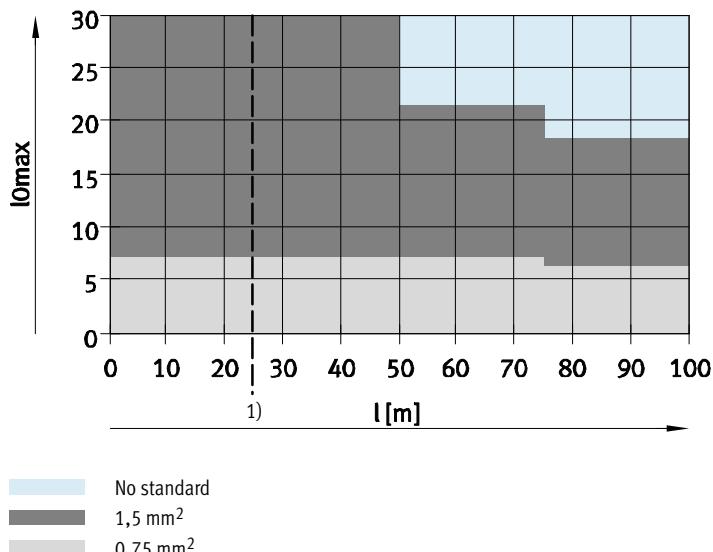
Technical data – Cables

Designation	Motor cable	
For motor	EMME-AS-40/60	EMME-AS-80/100
Type	NEBM-M16G8-...-Q7-...	NEBM-M16G8-...-Q9-...
Cable composition	2x (2x 0.25 mm ²) (3 A, 48 V, 0.5 KV) 4x 0.75 mm ² (12 A, 600 V, 2.5 KV)	2x (2x 0.5 mm ²) (8 A, 300 V, 2.5 KV) 4 x 1.5 mm ² (16 A, 600 V, 2.5 KV)
Degree of contamination	Screened	
Degree of contamination	3	
Min. bending radius [mm]	55	64
Ambient temperature [°C]	-50 ... +90	-50 ... +90
Ambient temperature ¹⁾ [°C]	-40 ... +90	-40 ... +90
Cable characteristics	Suitable for use with energy chains	
Protection class	IP65 (in assembled state)	
Material	Polyurethane	
Note on materials	RoHS-compliant	
CE marking (see declaration of conformity)	To EU Low Voltage Directive	

Designation	Encoder cable	
For motor	EMME-AS-40/60/80/100	
Type	NEBM-M12G8-...	
Cable composition	4x (2x 0.14 mm ²) Screened	
Degree of contamination	3	
Min. bending radius [mm]	68	
Ambient temperature [°C]	-40 ... +80	
Ambient temperature ¹⁾ [°C]	-5 ... +80	
Cable characteristics	Suitable for use with energy chains	
Protection class	IP65 (in assembled state)	
Material	Polyurethane	
Note on materials	RoHS-compliant	

1) With flexible cable installation

Recommended cable cross section as a function of cable length l and max. motor current I₀

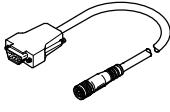


- 1) Cable lengths > 25 m possible following technical clarification; up to 100 m on request.

Servo motors EMME-AS

Accessories

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Ordering data	Cable length [m]	Part No.	Type
Motor cable			
		For EMME-AS-40/60 (cable cross section: 0.75 mm ²)	
	2.5	8004662	NEBM-M16G8-E-2.5-Q7-LE8
	5	8003770	NEBM-M16G8-E-5-Q7-LE8
	7.5	8004663	NEBM-M16G8-E-7.5-Q7-LE8
	10	8003771	NEBM-M16G8-E-10-Q7-LE8
	15	8003772	NEBM-M16G8-E-15-Q7-LE8
	X length ¹⁾	8003773	NEBM-M16G8-E-Q7-LE8
		For EMME-AS-80/100 (cable cross section: 1.5 mm ²)	
	2.5	8004660	NEBM-M16G8-E-2.5-Q9-LE8
	5	8003766	NEBM-M16G8-E-5-Q9-LE8
	7.5	8004661	NEBM-M16G8-E-7.5-Q9-LE8
	10	8003767	NEBM-M16G8-E-10-Q9-LE8
	15	8003768	NEBM-M16G8-E-15-Q9-LE8
	X length ¹⁾	8003769	NEBM-M16G8-E-Q9-LE8
Encoder cable			
		For EMME-AS-40/60/80/100	
	2.5	8004664	NEBM-M12G8-E-2.5-N-S1G15
	5	8003762	NEBM-M12G8-E-5-N-S1G15
	7.5	8004665	NEBM-M12G8-E-7.5-N-S1G15
	10	8003763	NEBM-M12G8-E-10-N-S1G15
	15	8003764	NEBM-M12G8-E-15-N-S1G15
	X length ¹⁾	8003765	NEBM-M12G8-E-N-S1G15

- 1) Max. 25 m. Cable lengths > 25 m possible following technical clarification; up to 100 m on request.
Available in 0.1 m increments.