Pneumatic-Pneumatic Positioner (Lever type/Rotary type)

Series IP5000/5100

• JIS F8007 IP55

• Fulfilling options: Opening indicator (IP5100), Built-in bypass (SIG-OUT1) (IP5000), Built-in equalizing valve (OUT1-OUT2) (IP5100)

How to Order

Pressure gauge/Air port Rc (Standard)

NPT

IP5 000 - 0 1 0						
Type ●						
000	Lever type	l:	nput pressu	re •		
100	Rotary type	0 0.	02 to 1 MPa (Stand	lard)		
		1 0.02 to 0.06 MPa 0.06 to 0.1 MPa				
	Pressure gauge ● Indication of opening Note) ●			f opening Note)		
0	None		0	Not provided		
1	0.2 MPa	1 Indicated		Indicated		
2	0.3 MPa	Note) IP5000 is available only with				
3	1 MPa	option "0" (no indication).				
Ambient temperature ● Nil						

-5 to 100°C (High temperature) -30 to 60°C (Low temperature)

Precautions	

- 1. Avoid impact to positioner while transporting and handling.
- 2. Operate within specified temperature range to prevent deterioration of seals.
- 3. Attach a body cover to the positioner when it is in use or left in the field in order to avoid rain water.
- 4. Take measures to avoid dew condensation if the positioner is exposed to high temperature and humidity during transportation or storage or when it is left on the site.
- 5. The zero point is subject to the mounting position. Adjust zero point after installation on the site.
- 6. As the positioner contains extra-fine orifices such as restrictor and nozzle, if drain or dust is present in the supply pressure line, malfunction (*1) may result. In addition to an air filter (SMC Series AF), it is recommended to use a mist separator (SMC Series AM, AFM) and a micro mist separator (SMC Series AMD, AFD).
- Also, refer to "SMC Air Preparation System" for air quality.
- 7. Never use a lubricator, as this can cause a malfunction (*1).
- *1 If the restrictor is clogged, output from the OUT1 port of the positioner may occur continuously or hunching and overshoot may occur.

• Accessories Note 1)				
Nil	None (Standard)	With standard lever (10 to 85 mm stroke) for IP5000		
A	ø0.7 Output restriction with pilot valve	Common to IP5000 and		
B ø1.0 Output restriction with pilot valve		IP5100 small capacity actuators		
С	Fork lever-type fitting M	Only for IDE 100		
D	Fork lever-type fitting S	Only for IP5100		
E	For stroke 35 to 100 mm with lever unit	Only for IP5000 Note 2)		
F	For stroke 50 to 140 mm with lever unit			

Note 1) If two or more accessories are required, the part numbers should be given in alphabetical order. Ex.) IP5000-010-AD

Note 2) For "E" and "F", standard lever is not provided.

Specifications

Nil

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Type	IP5000		IP5100	
, ,	Lever type lever feedback		Rotary type cam feedback	
Item	Single action	Double action	Single action	Double action
Supply pressure	0.14 to 0.7 MPa			
Input pressure	0.02 to 0.1 MPa			
Standard stroke	10 to 85 mm		60° to 100°	
Sensitivity	Within 0.1% F.S.		Within 0.5% F.S.	
Linearity	Within ±1% F.S.	Within ±2% F.S.		
Hysteresis	Within 0.75% F.S.	. Within 1% F.S.		
Repeatability	Within ±0.5% F.S.			
Air consumption	5 L/min (ANR) or less (SUP = 0.14 MPa)Note)		11 L/min (ANR) or less (SUP = 0.4 MPa)Note)	
Output flow rate	80 L/min (ANR) or more (SUP = 0.14 MPa)Note) 200 L/min (ANR) or more (SUP = 0.4 MPa)Note)		re (SUP = 0.4 MPa)Note)	
Ambient and fluid temperature	-20°C to 80°C (Standard)			
Coefficient of temperature	Within 0.1% F.S./°C			
Air connection port	Rc1/4 (Standard)			
Main component parts	Aluminum die-cast, Stainless steel, Brass, Nitrile rubber			
Weight	Approx. 1.4 kg		Approx. 1.2 kg	
Dimensions	118 x 102 x 86 (Body)		118 x 92 x 77.5 (Body)	

Note) Standard air temperature: 20°C (293 K), Absolute pressure: 760 mmHg (101.3 kPa), Relative humidity: 65%

Replacement Parts

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Part no.	Description	Note			
P378010-10	Pilot valve unit	For IP5000			
P378020-11	Pilot valve unit	For IP5100			
P368010-24	Fork lever assembly M	For IP5100 (Accessory: C)			
P368010-25	Fork lever assembly S	For IP5100 (Accessory: D)			
P378010-11	Feedback lever	For IP5000/10 to 85 mm (Accessory: Nil)			
P378010-12	Feedback lever	For IP5000/35 to 100 mm (Accessory: E)			
P378010-13	Feedback lever	For IP5000/50 to 140 mm (Accessory: F)			

Series IP5000/5100

Principle of Operation

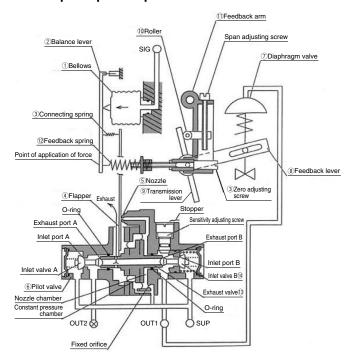
IP5000 type

When the input pressure applied to the SIG port of the positioner increases, bellows ① press balance lever ② to the left. As this movement moves flapper ④ to the left through connecting spring ③, the gap between nozzle ⑤ and flapper ④ widens, and the nozzle back pressure of pilot valve ⑥ drops. As a result, the pressure balance in the constant pressure chamber is broken, and exhaust valve ③ presses inlet valve B ④ to the right, thus opening inlet port B. Then, output pressure OUT1 rises, and driven diaphragm ⑦ moves downward

The movement of diaphragm valve ⑦ deflects feedback arm ① to the right through feedback lever ⑧, transmission lever ⑨, and roller ①. Such deflection increases the tension of feedback spring ⑫ and acts on balance lever ②.

Since driven diaphragm ${\mathfrak D}$ moves until the tensile force of feedback spring ${\mathfrak D}$ and the force generated by bellows ${\mathfrak D}$ balance, it is always set in the position proportional to the input pressure. When the signal air pressure decreases, the operation is reversed.

IP5000 principle of operation



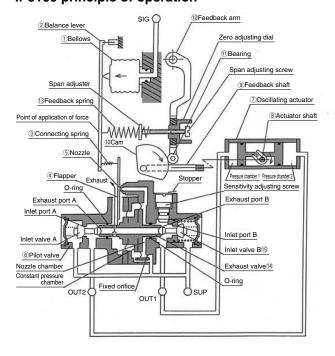
IP5100 type

When the input pressure applied to the SIG port of the positioner increases, bellows ① press balance lever ② to the left. As this movement moves flapper ④ to the left through connecting spring ③, the gap between nozzle ⑤ and flapper ④ widens, and the nozzle back pressure of pilot valve ⑥ drops. As a result, the pressure balance in the constant pressure chamber is broken, and exhaust valve ④ presses inlet valve B ⑤ to the right. Then, inlet port B opens, and output pressure OUT1 increases.

In the meantime, the movement of exhaust valve ⁽⁴⁾ to the right opens exhaust port A, and output pressure OUT2 decreases. Therefore, pressure difference is generated between pressure chamber 1 and pressure chamber 2 of oscillating actuator ⁽⁷⁾, and actuator shaft ⁽⁸⁾ turns in the direction of the arrow. The movement of actuator shaft ⁽⁸⁾ deflects feedback arm ⁽¹⁾ to the right through feedback shaft ⁽⁹⁾, cam ⁽¹⁾, and bearing ⁽¹⁾. Such deflection increases the tension of feedback spring ⁽³⁾ and acts on balance lever ⁽²⁾.

Since oscillating actuator $\widehat{\mathcal{D}}$ moves until the tensile force of feedback spring $\widehat{\mathbb{G}}$ and the force generated by bellows $\widehat{\mathbb{G}}$ balance, it is always set in the position proportional to the input pressure. When the signal air pressure decreases, the operation is reversed.

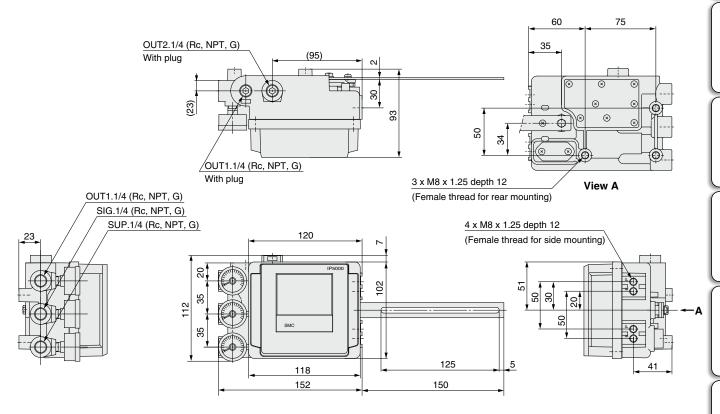
IP5100 principle of operation



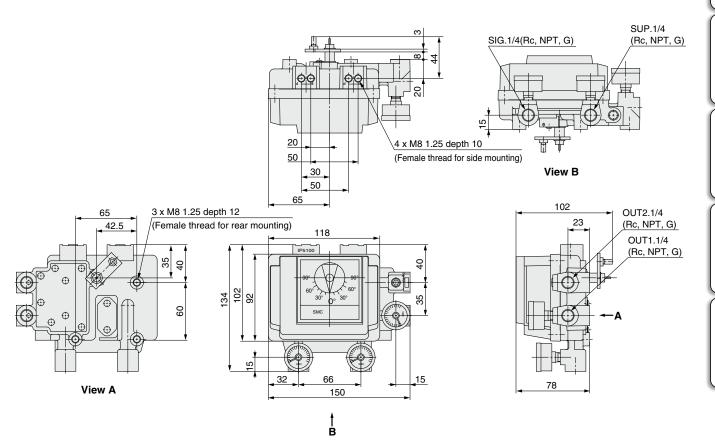


Dimensions

IP5000 type (Lever type lever feedback)



IP5100 type (Rotary type cam feedback)



SMC