

# Parallel grippers DHPS



# Parallel grippers DHPS

Key features

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## At a glance

### General information

- Resilient and precise T-slot guide of the gripper jaws
- Oval piston for high gripping forces
- High gripping forces with compact dimensions
- Gripper jaw centring options
- Max. repetition accuracy
- Gripping force retention
- Internal fixed flow control
- Wide range of options for mounting on drive units

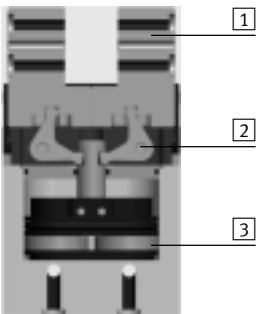
- Sensor technology:
  - Adaptable position sensor for the small grippers
  - Integratable proximity sensors for the medium and large grippers

### Flexible range of applications

- Can be used as a double-acting and single-acting gripper
- Compression spring for supplementary or retaining gripping forces
- Suitable for external and internal gripping

## The technology in detail

### Gripper closed



### Gripper open



- 1 Gripper jaw
- 2 Reversing lever
- 3 Piston with magnet

-  - Note

Gripper selection  
sizing software

→ [www.festo.com](http://www.festo.com)

## Position sensing/force control

### With position transmitter SMAT-8M



Analogue positional feedback possible

- Analogue output 0 ... 10 V

### With proportional pressure regulator VPPM



Infinite adjustment of the gripping force possible

- Setpoint input
  - 0 ... 10 V
  - 4 ... 20 mA

### With proximity sensor SMT-8G/-10G



Multiple positions can be sensed:

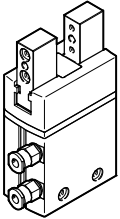
- Open
- Closed
- Workpiece gripped

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Key features

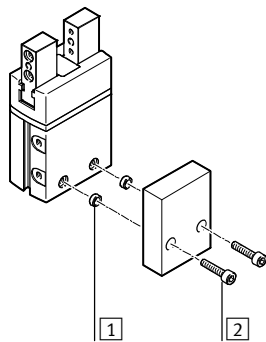
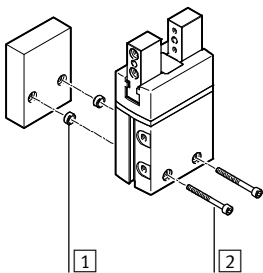
## Supply ports

At the side

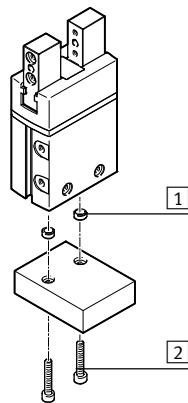


## Mounting options

At the side

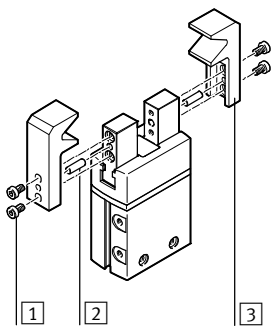


From underneath



- 1 Centring sleeves
- 2 Mounting screws

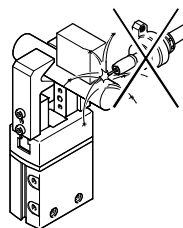
## Mounting options for external gripper fingers



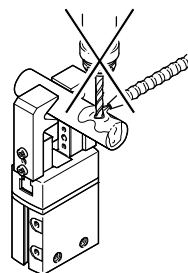
- 1 Mounting screws
- 2 Centring pins
- 3 Gripper fingers

Note

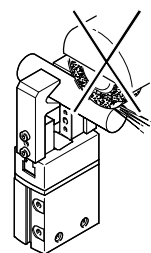
These grippers are not designed for the following or similar sample applications:



- Welding spatter



- Machining
- Aggressive media



- Grinding dust

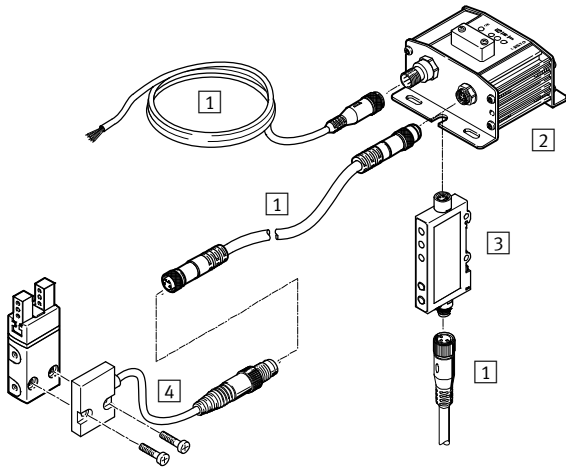
# Parallel grippers DHPS

Peripherals overview

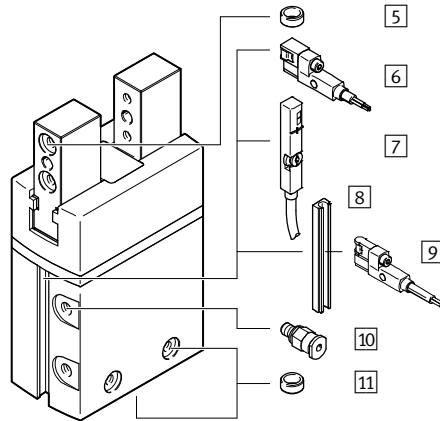
FESTO

## Peripherals overview

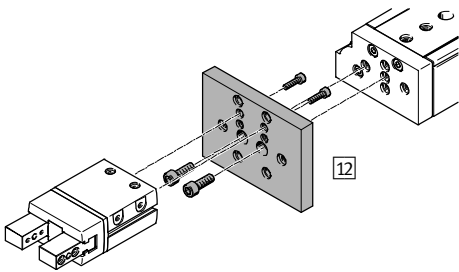
DHPS-06



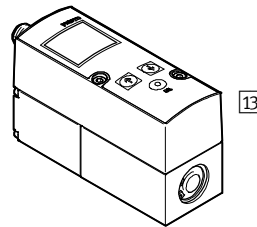
DHPS-10 ... 35



## System product for handling and assembly technology



## Proportional pressure regulator VPPM



# Parallel grippers DHPS

Peripherals overview

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Accessories			
	Type	Brief description	→ Page/Internet
1	Connecting cable NEBU	For connecting evaluation unit and signal converter	22
2	Evaluation unit SMH-AE1	<ul style="list-style-type: none"> <li>For evaluating signals for position sensor SMH-S1</li> <li>For size 6</li> </ul>	22
3	Signal converter SVE4	<ul style="list-style-type: none"> <li>For evaluating signals for position sensor SMH-S1</li> <li>For size 6</li> </ul>	22
4	Position sensor SMH-S1	<ul style="list-style-type: none"> <li>Adaptable and integratable sensor technology, for sensing the piston position</li> <li>For size 6</li> </ul>	21
5	Centring sleeve ZBH	<ul style="list-style-type: none"> <li>For centring the gripper fingers on the gripper jaws</li> <li>The delivery scope of the gripper for size 10 and above includes 4 centring sleeves</li> </ul>	21
6	Proximity sensor SMT-8G	<ul style="list-style-type: none"> <li>For sensing the piston position</li> <li>Proximity sensor does not project past the housing at the bottom</li> <li>For size 10 ... 35</li> </ul>	23
7	Position transmitter SMAT-8M	<ul style="list-style-type: none"> <li>Continuously senses the position of the piston. Has an analogue output with an output signal in proportion to the piston position.</li> <li>For size 10 ... 35</li> </ul>	23
8	Bondable sensor rail HGP-SL	<ul style="list-style-type: none"> <li>Enables the use of proximity sensors SME/SMT-10</li> <li>For size 10 ... 35</li> </ul>	21
9	Proximity sensor SMT-10G	<ul style="list-style-type: none"> <li>For sensing the piston position</li> <li>Proximity sensor does not project past the housing at the bottom</li> <li>With sensor rail HGP-SL10-...</li> <li>For size 10 ... 35</li> </ul>	23
10	Push-in fitting QS	For connecting compressed air tubing with standard O.D.	quick star
11	Centring sleeve ZBH	<ul style="list-style-type: none"> <li>For centring the gripper when mounting</li> <li>The scope of delivery of the gripper includes 2 centring sleeves</li> </ul>	21
12	Adapter kit DHAA, HMSV, HAPG, HAPS, HMVA	Connecting plate between drive and gripper	16
13	Proportional pressure regulator VPPM	For infinite adjustment of the gripping force	vppm

# Parallel grippers DHPS

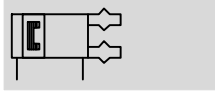
Type codes

		DHPS	-	16	-	A	-	
<b>Type</b>								
DHPS	Parallel gripper							
<b>Size</b>								
<b>Position sensing</b>								
A	Via proximity sensor							
<b>Gripping force retention</b>								
NO	Opening							
NC	Closing							

# Parallel grippers DHPS

Technical data

Function  
Double-acting  
DHPS-...-A



Size  
6 ... 35 mm

Total stroke  
4 ... 25 mm

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Function – Variants  
Single-acting or  
with gripping force retention ...  
... opening DHPS-...-NO



... closing DHPS-...-NC



General technical data		6	10	16	20	25	35
Design		Lever Forced motion sequence					
Mode of operation		Double-acting					
Gripper function		Parallel					
Guide		Plain-bearing guide					
Gripping force retention		–	NO, NC	NO, NC	NO, NC	NO, NC	NO, NC
Number of gripper jaws		2					
Max. load per external gripper finger <sup>1)</sup>	[g]	10	60	150	250	350	450
Stroke per gripper jaw	[mm]	2	3	5	6.5	7.5	12.5
Pneumatic connection		M3	M3	M3	M5	G1/8	G1/8
Repetition accuracy <sup>2)</sup>	[mm]	±0.02					
Max. interchangeability	[mm]	±0.2					
Max. operating frequency	[Hz]	4			3		2
Rotational symmetry	[mm]	< Ø 0.2					
Position sensing		Via position sensor		Via proximity sensor, position transmitter			
Type of mounting		Via through-hole and centring sleeve Via female thread and centring sleeve					
Mounting position		Any					

1) Valid for unthrottled operation

2) End-position drift under constant conditions of use with 100 consecutive strokes in the direction of movement of the gripper jaws

Operating and environmental conditions		6	10	16	20	25	35
Min. operating pressure							
DHPS-...-A	[bar]	2					
DHPS-...-A-N	[bar]	–	4				
Max. operating pressure	[bar]	8					
Operating medium		Compressed air in accordance with ISO 8573-1:2010 [7:4:4]					
Note on operating/pilot medium		Operation with lubricated medium possible (in which case lubricated operation will always be required)					
Ambient temperature <sup>1)</sup>	[°C]	+5 ... +60					
Corrosion resistance class CRC <sup>2)</sup>		1					

1) Note operating range of proximity sensors

2) CRC1: Corrosion resistance class to Festo standard 940 070

Components with light corrosion exposure. Protection for transport and storage. Components without significant decorative function or surface, e.g. installed out of sight internally or behind covers.

# Parallel grippers DHPS

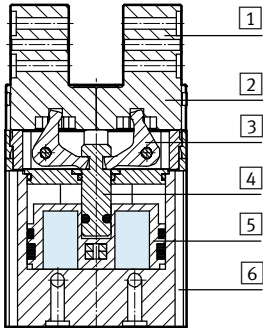
Technical data

FESTO

Weight [g]						
Size	6	10	16	20	25	35
DHPS-...-A	19	67	184	380	700	1,285
DHPS-...-A-N	-	68	188	387	713	1,345

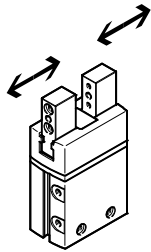
## Materials

Sectional view



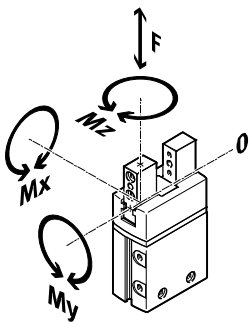
Parallel gripper		
1	Gripper jaw	High-alloy stainless steel
2	Cover cap	Polyamide
3	Reversing lever	Hardened sintered steel
4	Piston rod	Tempered steel
5	Piston	Polyacetal
6	Housing	Hard anodised wrought aluminium alloy
-	Seals	Nitrile rubber
-	Note on materials	Free of copper and PTFE RoHS-compliant

## Gripping force [N] at 6 bar



Size	6	10	16	20	25	35	
Gripping force per gripper jaw							
DHPS-...-A	Opening	15	39	105	162	249	483
	Closing	13.5	34.5	96	147	228	450
Total gripping force							
DHPS-...-A	Opening	30	80	210	320	500	970
	Closing	25	70	190	290	450	910

## Characteristic load values at the gripper jaws



The indicated permissible forces and torques apply to a single gripper jaw. They include the lever arm, additional applied loads due to the workpiece or external gripper fingers and

acceleration forces occurring during movement.

The zero coordinate line (gripper jaw guide) must be taken into consideration for the calculation of torques.

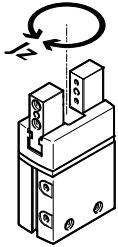
Size	6	10	16	20	25	35	
Max. permissible force $F_z$	[N]	10	60	150	250	350	450
Max. permissible torque $M_x$	[Nm]	0.5	3	8	14	30	50
Max. permissible torque $M_y$	[Nm]	0.5	3	8	14	30	50
Max. permissible torque $M_z$	[Nm]	0.5	3	8	14	30	50



# Parallel grippers DHPS

Technical data

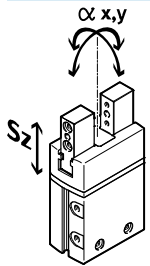
## Mass moment of inertia [kgm<sup>2</sup>x10<sup>-4</sup>]



Mass moment of inertia of the parallel gripper in relation to the central axis, without external gripper fingers, without load.

Size	6	10	16	20	25	35
DHPS-...-A	0.01	0.08	0.47	1.49	3.83	12.70
DHPS-...-A-NO	–	0.08	0.47	1.52	3.92	12.83
DHPS-...-A-NC	–	0.08	0.47	1.49	3.84	12.73

## Gripper jaw backlash



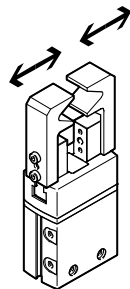
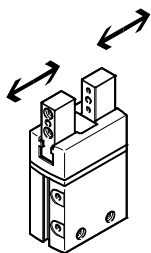
The plain-bearing guide used in the grippers means that there is backlash between the gripper jaws and the housing. The values entered in the table for the backlash were calculated in accordance with the traditional accumulative tolerance method.

Size	6	10	16	20	25	35
Max. gripper jaw backlash Sz	[mm]	≤D.02				
Max. gripper jaw angular backlash ax, ay	[°]	≤1	≤D.5			

## Opening and closing times [ms] at 6 bar

Without external gripper fingers

With external gripper fingers



The indicated opening and closing times [ms] were measured at room temperature at an operating pressure of 6 bar with horizontally mounted grippers without additional gripper

fingers. The grippers must be throttled for greater loads [g]. Opening and closing times must then be adjusted accordingly.

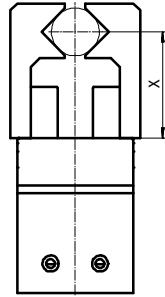
Size		6	10	16	20	25	35
Without external gripper fingers							
DHPS-...-A	Opening	8	21	33	59	48	95
	Closing	17	28	41	87	63	123
DHPS-...-A-NO	Opening	–	19	32	58	45	88
	Closing	–	30	50	97	78	151
DHPS-...-A-NC	Opening	–	58	48	72	68	131
	Closing	–	24	37	62	52	99
With external gripper fingers (as a function of the load)							
DHPS-...	20 g	50	–	–	–	–	–
	100 g	–	50	–	–	–	–
	125 g	–	100	–	–	–	–
	150 g	–	200	–	–	–	–
	200 g	–	–	100	–	–	–
	250 g	–	–	200	–	–	–
	300 g	–	–	300	100	–	–
	350 g	–	–	–	200	–	–
	400 g	–	–	–	300	100	–
	500 g	–	–	–	–	200	–
	600 g	–	–	–	–	300	200
750 g	–	–	–	–	–	300	

# Parallel grippers DHPS

Technical data

## Gripping force $F_H$ per gripper jaw as a function of operating pressure and lever arm $x$

The gripping forces as a function of operating pressure and lever arm can be determined from the following graphs.

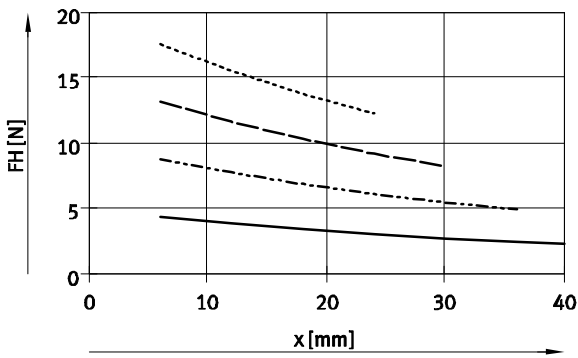


Note  
Gripper selection  
sizing software  
→ [www.festo.com](http://www.festo.com)

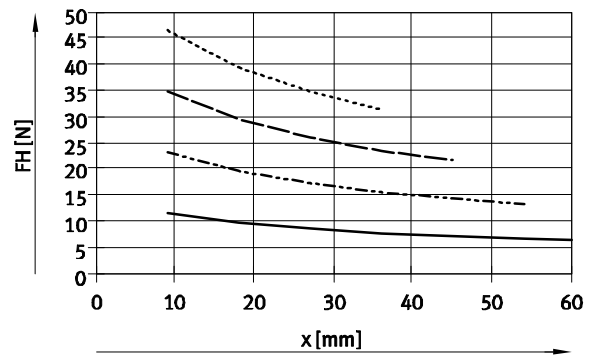
- 2 bar
- - - 4 bar
- · - 6 bar
- · · 8 bar

### External gripping (closing)

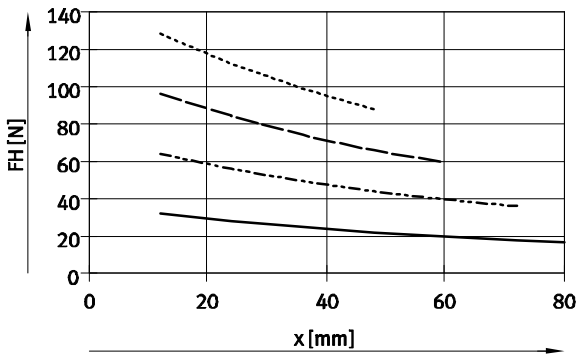
DHPS-06



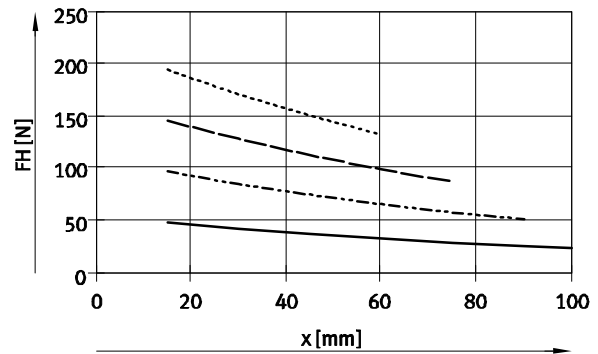
DHPS-10



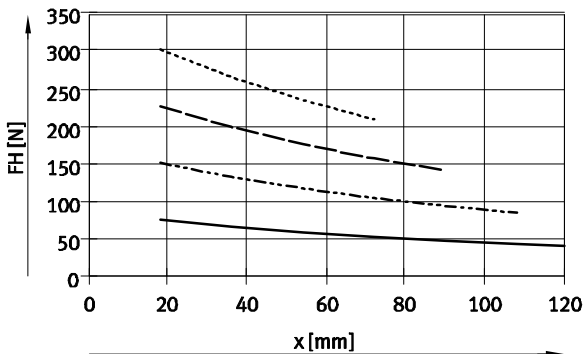
DHPS-16



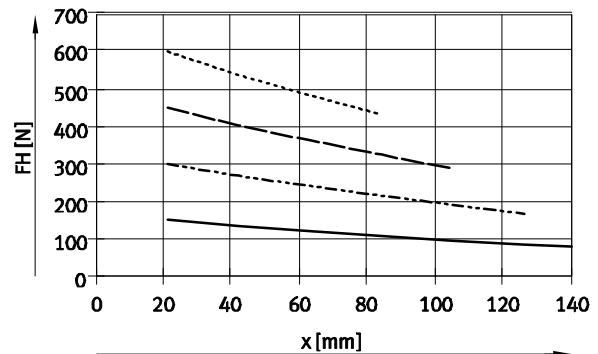
DHPS-20



DHPS-25



DHPS-35

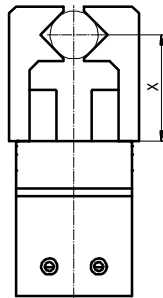


# Parallel grippers DHPS

Technical data

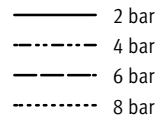
## Gripping force $F_H$ per gripper jaw as a function of operating pressure and lever arm $x$

The gripping forces as a function of operating pressure and lever arm can be determined from the following graphs.



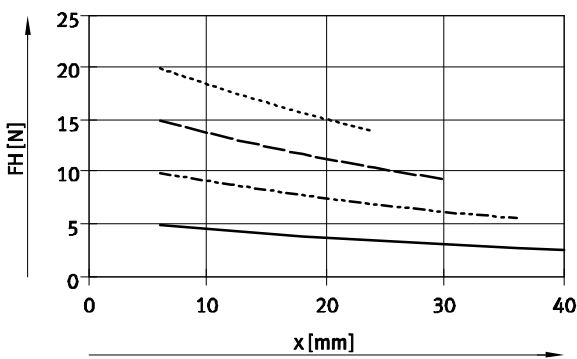
Note

Gripper selection  
sizing software  
→ [www.festo.com](http://www.festo.com)

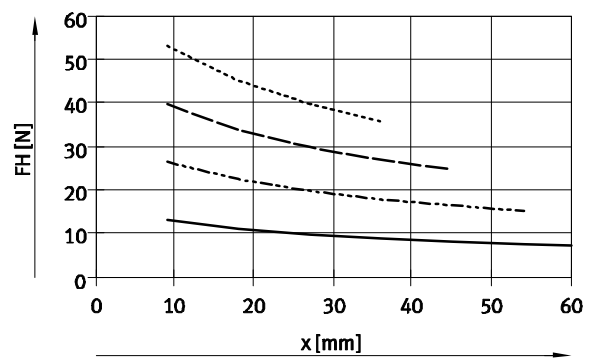


### Internal gripping (opening)

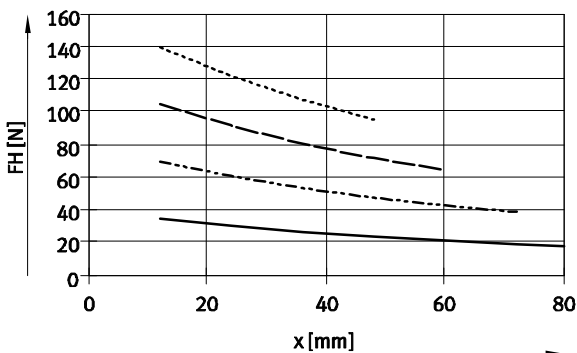
DHPS-06



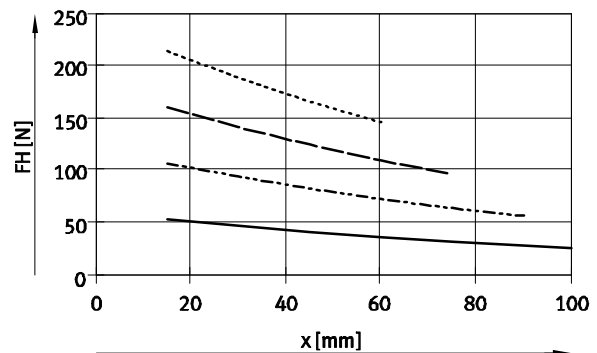
DHPS-10



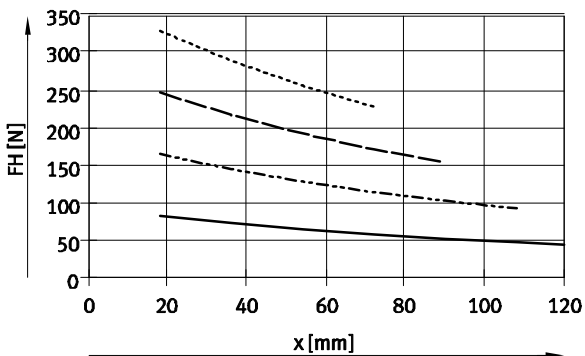
DHPS-16



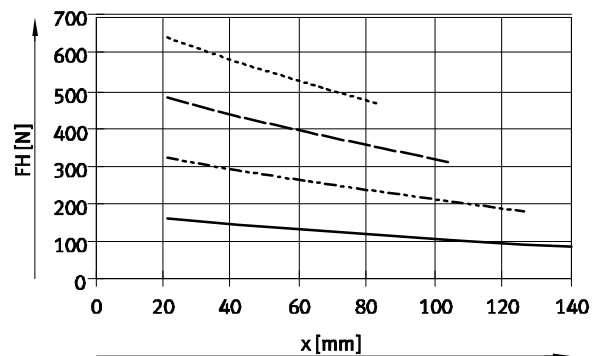
DHPS-20



DHPS-25



DHPS-35



# Parallel grippers DHPS

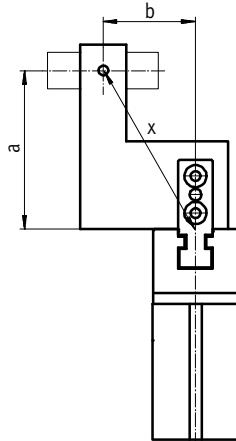
Technical data

## Gripping force $F_H$ per gripper jaw at 6 bar as a function of lever arm $x$ and eccentricity $a$ and $b$

The following formula must be used to calculate the lever arm  $x$  with eccentric gripping:

$$x = \sqrt{a^2 + b^2}$$

The gripping force  $F_H$  can be read from the graphs (→ 10/11) using the calculated value  $x$ .



### Calculation example

Given:

Distance  $a = 25$  mm

Distance  $b = 20$  mm

To be calculated:

The gripping force at 6 bar, with a DHPS-16, used as an external gripper

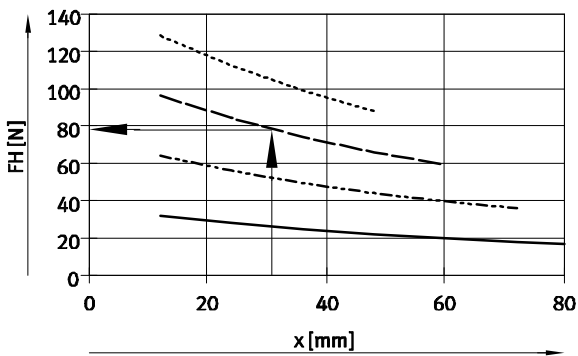
Procedure:

Calculating the lever arm  $x$

$$x = \sqrt{25^2 + 20^2}$$

$$x = 32$$
 mm

The graph (→ 10) gives a value of  $F_H = 79$  N for the gripping force.



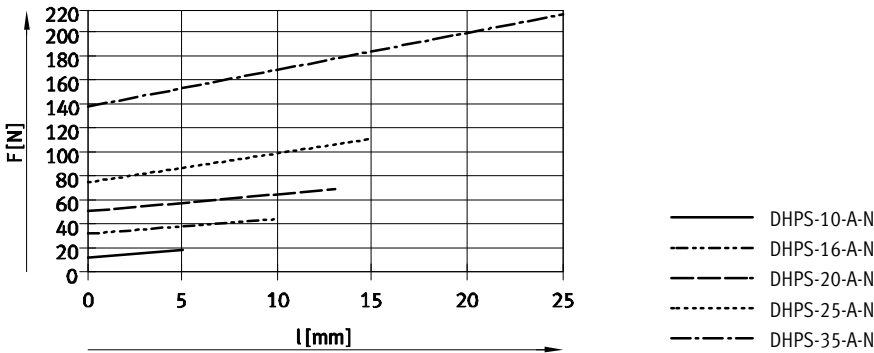
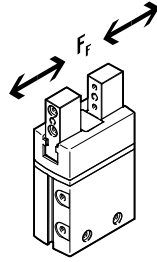
# Parallel grippers DHPS

Technical data

## Spring force $F_F$ as a function of size and total gripper jaw stroke $l$

Gripping force retention for DHPS-...-N...

The spring forces  $F_F$  as a function of gripper jaw stroke  $l$  can be determined from the following graph.



## Spring force $F_F$ as a function of size, gripper jaw stroke $l$ and lever arm $x$ per gripper finger

The lever arm  $x$  must be taken into consideration when determining the actual spring force  $F_{Ftotal}$ . The formulae for calculating the spring force are provided in the table below.

Gripping force retention	Size	$F_{Ftotal}$ per gripper finger
NO, NC	10	$-0.02 * x + 0.5 * F_F$
	16	$-0.08 * x + 0.5 * F_F$
	20	$-0.1 * x + 0.5 * F_F$
	25	$-0.12 * x + 0.5 * F_F$
	35	$-0.19 * x + 0.5 * F_F$

## Determination of the actual gripping forces $F_{Gr}$ for DHPS-...-NO and DHPS-...-NC as a function of application

The parallel grippers with integrated spring type DHPS-...-NO (opening gripping force retention) and DHPS-...-NC (closing gripping force retention) can be used as

- single-acting grippers

- grippers with supplementary gripping force and
- grippers with gripping force retention depending on requirements.

In order to calculate the available gripping forces  $F_{Gr}$  (per gripper jaw), the gripping force ( $F_H$ ) and spring force ( $F_{Ftotal}$ ) must be combined accordingly.

### Application

Single-acting

Supplementary gripping force

Gripping force retention

- Gripping with spring force:  
 $F_{Gr} = F_{Ftotal}$

- Gripping with pressure and spring force:  
 $F_{Gr} = F_H + F_{Ftotal}$

- Gripping with spring force:  
 $F_{Gr} = F_{Ftotal}$

- Gripping with pressure force:  
 $F_{Gr} = F_H - F_{Ftotal}$

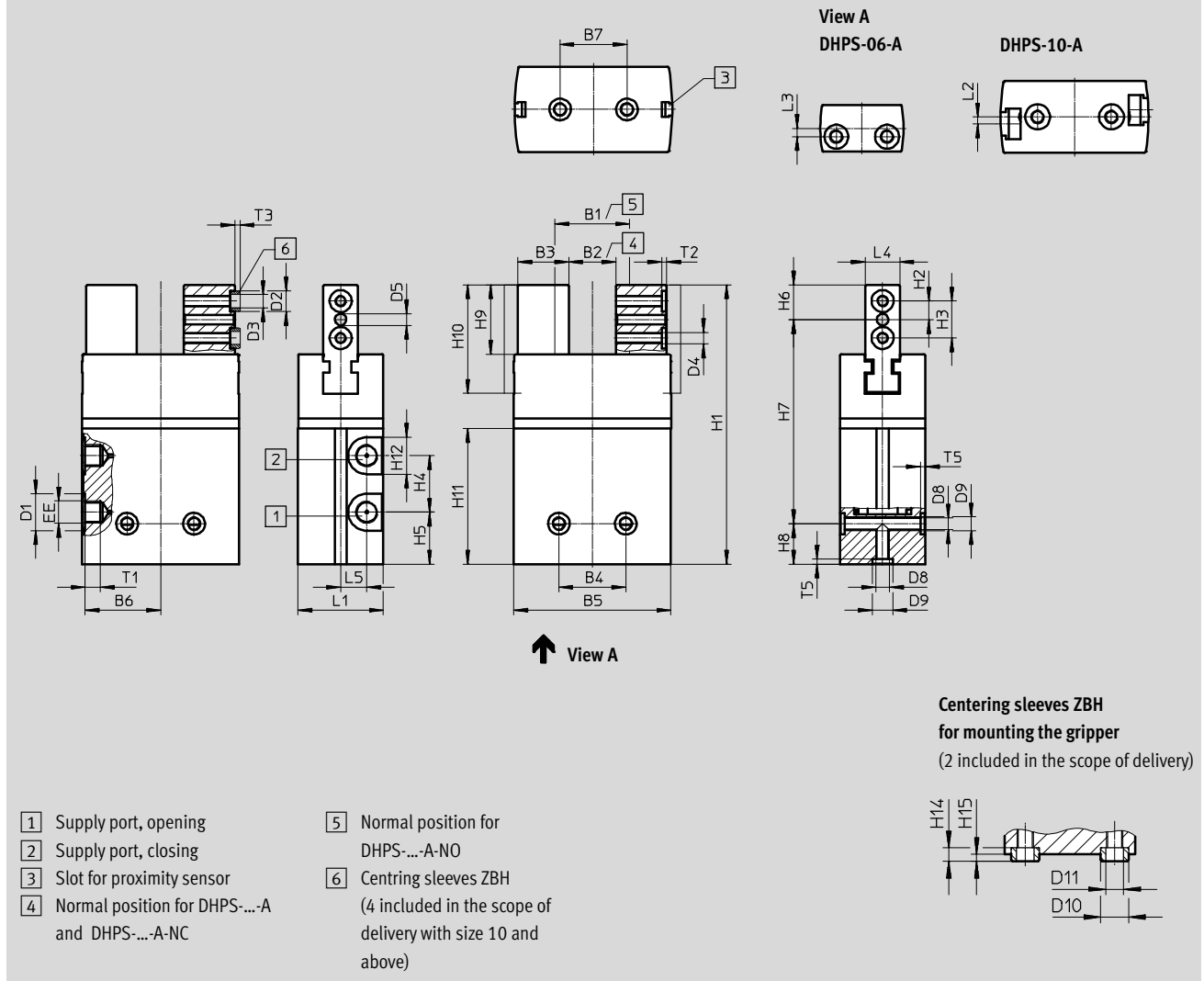
# Parallel grippers DHPS

Technical data

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## Dimensions

Download CAD data → [www.festo.com](http://www.festo.com)



Size	B1	B2	B3	B4 <sup>1)</sup>	B5	B6	B7 <sup>1)</sup>	D1	D2	D3	D4	D5	D8	D9
[mm]	±0.5	±0.5	-0.03		±0.1			∅	∅ H8/h7	∅		∅ H8	∅ +0,1	
6	10	6	5.5	11	18	8.65	11	7	-	-	M2	1.5	2.5	M3
10	21.8	15.8	7	16	32	15.4	16	7	5	3.2	M3	2	2.5	M3
16	27.8	17.8	13	25	47	22.65	25	7	7	5.3	M4	3	3.3	M4
20	30	17	17.5	25	55.6	26.65	25	10	7	5.3	M4	4	3.3	M4
25	35.4	20.4	22	29	68.2	32.65	29	16	9	6.4	M5	4	5.1	M6
35	56	31	27	33	88	42.25	33	16	9	6.4	M6	5	6.4	M8

1) Tolerance for centring hole ±0.02 mm; tolerance for thread ±0.1 mm

# Parallel grippers DHPS

Technical data

Size [mm]	D10 ∅ h7	D11 ∅	EE	H1	H2	H3 <sup>1)</sup>	H4	H5	H6	H7 ±0.2	H8 <sup>2)</sup>	H9	H10
6	–	–	M3	45.5	2.9	5.8	15	4	5	33	7.5	9.55	15.8
10	5	3.2	M3	66	4	8	15.5	10.5	7.5	51	7.5	15.2	23
16	7	5.3	M3	80	5.5	11	18	11	10	62.5	7.5	20	32.5
20	7	5.3	M5	101	7	14	23	16	12.5	81	7.5	25	39.5
25	9	6.4	G $\frac{1}{8}$	121	8	16	24.5	22.5	15	88.5	17.5	30	47
35	9	6.4	G $\frac{1}{8}$	142	8.5	17	29	24	16	108.5	17.5	32	53

Size [mm]	H11	H12	H14 –0.2	H15 –0.3	L1	L2	L3 <sup>1)</sup>	L4 –0.05	L5	T1 +0.5	T2 +0.1	T3 –0.2	T5 +0.1
6	25.3	7	–	–	10 <sup>+0,1</sup>	–	1.8	5	1.5	3.5	–	–	1.2
10	35	7	2.4	1.2	15.5 <sup>+0,1</sup>	1.5	–	7	5	5	1.2	1.2	1.2
16	38.1	7	3	1.4	22 <sup>+0,1</sup>	–	–	10	7	6	1.6	1.4	1.6
20	50	10	3	1.4	30±0,1	–	–	12	9	6	1.6	1.4	1.6
25	58.8	16	4	1.9	37±0,1	–	–	15	11.3	6.5	2.1	1.9	2.1
35	65.3	16	4	1.9	45 <sup>+0,1</sup>	–	–	20	13.5	6.5	2.1	1.9	2.6

1) Tolerance for centring hole ±0.02 mm; tolerance for thread ±0.1 mm

2) Tolerance for centring hole –0.05 mm; tolerance for thread ±0.1 mm

Ordering data						
Size [mm]	Double-acting without compression spring		Single-acting or with gripping force retention			
	Part No.	Type	Opening		Closing	
	Part No.	Type	Part No.	Type	Part No.	Type
6	1254039	DHPS-06-A	–	–	–	–
10	1254040	DHPS-10-A	1254041	DHPS-10-A-NO	1254042	DHPS-10-A-NC
16	1254043	DHPS-16-A	1254044	DHPS-16-A-NO	1254045	DHPS-16-A-NC
20	1254046	DHPS-20-A	1254047	DHPS-20-A-NO	1254048	DHPS-20-A-NC
25	1254049	DHPS-25-A	1254050	DHPS-25-A-NO	1254051	DHPS-25-A-NC
35	1254052	DHPS-35-A	1254053	DHPS-35-A-NO	1254054	DHPS-35-A-NC


# Parallel grippers DHPS



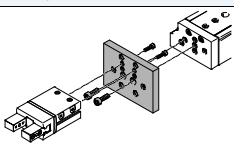
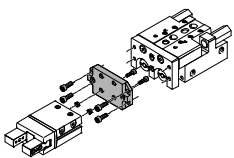
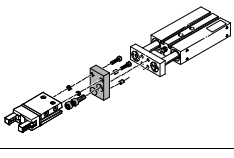
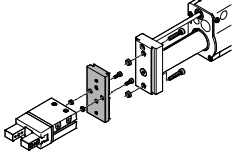
Accessories



**Adapter kit**  
HMSV, HAPG, HAPS

Material:  
Wrought aluminium alloy  
Free of copper and PTFE  
RoHS-compliant

 Note  
The kit includes the individual mounting interface as well as the necessary mounting material.

Permissible drive/gripper combinations with adapter kit						Download CAD data → <a href="http://www.festo.com">www.festo.com</a>	
Combination	Drive Size	Gripper Size	Mounting option		Adapter kit		
					CRC <sup>1)</sup>	Part No.	Type
<b>DGSL/DHPS</b>	DGSL	DHPS			HMSV		
	4, 6	6	■	■	2	548783	HMSV-53
	8, 10	10	■	■		548784	HMSV-54
	12, 16	16	■	■		548785	HMSV-55
	20, 25	20, 25	■	■		548786	HMSV-56
<b>SLT/DHPS</b>	SLT	DHPS			HAPS		
	6	6	■	–	2	178447	HAPS-1
	16	10	■	–		178449	HAPS-3
	20	16, 20	■	–		178450	HAPS-4
	25	25	■	–		178451	HAPS-5
<b>DPZ/DHPS</b>	DPZ	DHPS			HAPG		
	10, 16	10	■	–	2	163250	HAPG-1
	16	16, 20	■	–		163251	HAPG-2
	20	16, 20	■	–		163252	HAPG-3
	25, 32	25	■	–		163253	HAPG-4
<b>HMP/DHPS</b>	HMP	DHPS			HMSV		
	Direct mounting				2		
	16, 20	10	■	■		177666	HMSV-20
	16, 20, 25	16, 20	■	■		177761	HMSV-21
	16, 20, 25, 32	25	■	■		177762	HMSV-22
	25	35	■	■		177763	HMSV-23
	32	35	■	■		177764	HMSV-24
	Dovetail mounting				2		
	16, 20	10	■	■		177767	HMSV-27
	16, 20, 25	16, 20	■	■		177768	HMSV-28
	16, 20, 25, 32	25	■	■		177769	HMSV-29
	25	35	■	■		177770	HMSV-30
	32	35	■	■		178211	HMSV-31

1) Corrosion resistance class 2 according to Festo standard 940 070  
Components subject to moderate corrosion stress. Externally visible parts with primarily decorative surface requirements which are in direct contact with a normal industrial environment or media such as coolants or lubricating agents.




# Parallel grippers DHPS



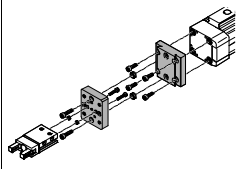
Accessories



**Adapter kit**  
HMSV, HAPG, HMVA

Material:  
Wrought aluminium alloy  
Free of copper and PTFE  
RoHS-compliant

 Note  
The kit includes the individual mounting interface as well as the necessary mounting material.

Permissible drive/gripper combinations with adapter kit					Download CAD data → <a href="http://www.festo.com">www.festo.com</a>		
Combination	Drive Size	Gripper Size	Mounting option		Adapter kit		
					CRC <sup>1)</sup>	Part No.	Type
DGP..., DGE-..., DGEA/DHPS	DG...	DHPS			HMVA, HAPG, HMSV		
	Direct mounting						
	18 <sup>2)</sup> , 25, 32 <sup>3)</sup>	6	<input type="checkbox"/>	<input type="checkbox"/>	2	196788	HMVA-DLA18/25
			<input type="checkbox"/>	<input type="checkbox"/>		192706	HAPG-37-S1
	40	6	<input type="checkbox"/>	<input type="checkbox"/>		196790	HMVA-DLA40
			<input type="checkbox"/>	<input type="checkbox"/>		192706	HAPG-37-S1
	18 <sup>2)</sup> , 25, 32 <sup>3)</sup>	10	<input type="checkbox"/>	<input type="checkbox"/>		196788	HMVA-DLA18/25
			<input type="checkbox"/>	<input type="checkbox"/>		192705	HAPG-36-S1
	40	10	<input type="checkbox"/>	<input type="checkbox"/>		196790	HMVA-DLA40
			<input type="checkbox"/>	<input type="checkbox"/>		192705	HAPG-36-S1
	18 <sup>2)</sup> , 25, 32 <sup>3)</sup>	16	<input type="checkbox"/>	<input type="checkbox"/>		196788	HMVA-DLA18/25
			<input type="checkbox"/>	<input type="checkbox"/>		193922	HAPG-37-S4
	40	16	<input type="checkbox"/>	<input type="checkbox"/>		196790	HMVA-DLA40
			<input type="checkbox"/>	<input type="checkbox"/>		193922	HAPG-37-S4
	Dovetail mounting						
	18 <sup>2)</sup> , 25	10	<input type="checkbox"/>	<input type="checkbox"/>	2	196788	HMVA-DLA18/25
			<input type="checkbox"/>	<input type="checkbox"/>		177767	HMSV-27
	32 <sup>3)</sup>	10	<input type="checkbox"/>	<input type="checkbox"/>		196789	HMVA-DL32
			<input type="checkbox"/>	<input type="checkbox"/>		177767	HMSV-27
	40	10	<input type="checkbox"/>	<input type="checkbox"/>		196790	HMVA-DLA40
			<input type="checkbox"/>	<input type="checkbox"/>		177767	HMSV-27
18 <sup>2)</sup> , 25	16	<input type="checkbox"/>	<input type="checkbox"/>	196788		HMVA-DLA18/25	
		<input type="checkbox"/>	<input type="checkbox"/>	177768		HMSV-28	
32 <sup>3)</sup>	16	<input type="checkbox"/>	<input type="checkbox"/>	196789		HMVA-DL32	
		<input type="checkbox"/>	<input type="checkbox"/>	177768		HMSV-28	
40	16	<input type="checkbox"/>	<input type="checkbox"/>	196790		HMVA-DLA40	
		<input type="checkbox"/>	<input type="checkbox"/>	177768		HMSV-28	
32 <sup>3)</sup>	25	<input type="checkbox"/>	<input type="checkbox"/>	196790		HMVA-DL32	
		<input type="checkbox"/>	<input type="checkbox"/>	177769		HMSV-29	
40	25	<input type="checkbox"/>	<input type="checkbox"/>	196790		HMVA-DLA40	
		<input type="checkbox"/>	<input type="checkbox"/>	177769		HMSV-29	
40	35	<input type="checkbox"/>	<input type="checkbox"/>	196790	HMVA-DLA40		
		<input type="checkbox"/>	<input type="checkbox"/>	177770	HMSV-30		

1) Corrosion resistance class 2 according to Festo standard 940 070  
Components subject to moderate corrosion stress. Externally visible parts with primarily decorative surface requirements which are in direct contact with a normal industrial environment or media such as coolants or lubricating agents.

2) Only for DGEA-...

3) Only for DGPL/DGPIL-...


# Parallel grippers DHPS



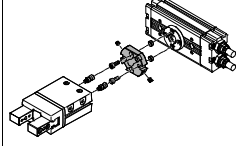
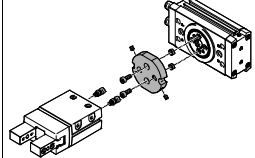
Accessories

FESTO

Adapter kit  
DHAA, HAPG

Material:  
Wrought aluminium alloy  
Free of copper and PTFE  
RoHS-compliant

 Note  
The kit includes the individual mounting interface as well as the necessary mounting material.

Permissible drive/gripper combinations with adapter kit						Download CAD data → <a href="http://www.festo.com">www.festo.com</a>	
Combination	Drive Size	Gripper Size	Mounting option		Adapter kit		
					CRC <sup>1)</sup>	Part No. Type	
	DRQD-...-FW		DHPS		HAPG		
	6, 8, 12	6	■	■	2	187568 HAPG-34	
	16 <sup>2)</sup>	6	■	■		187566 HAPG-SD2-12	
	16 <sup>2)</sup>	10	■	■		184477 HAPG-SD2-1	
	16 <sup>2)</sup>	16	■	■		184478 HAPG-SD2-2	
	20 <sup>2)</sup>	16, 20	■	■		184479 HAPG-SD2-3	
	20 <sup>2)</sup>	25	■	■		184480 HAPG-SD2-4	
	25 <sup>3)</sup>	16, 20	■	■		184482 HAPG-SD2-6	
	25 <sup>3)</sup>	25	■	■		184483 HAPG-SD2-7	
	32 <sup>3)</sup>	25	■	■		184485 HAPG-SD2-9	
	32 <sup>3)</sup>	35	■	■		184486 HAPG-SD2-10	
	40, 50	35	■	■	526027 HAPG-SD2-21		
	DRQD-...ZW		DHPS		HAPG		
	16	10	■	■	2	163267 HAPG-18	
	16	16, 20	■	■		163268 HAPG-19	
	20	16, 20	■	■		163269 HAPG-20	
	20	25	■	■		163270 HAPG-21	
	25	25	■	■		163271 HAPG-22	
		DRRD		DHPS		DHAA	
		8	6	■	■	2	2808892 DHAA-G-Q11-8-B1-6
10		6	■	■	2807644 DHAA-G-Q11-10-B1-6		
12		6	■	■	2805783 DHAA-G-Q11-12-B1-6		
12		10	■	■	2802687 DHAA-G-Q11-12-B1-10		
16		10	■	■	2190504 DHAA-G-Q11-16-B1-10		
16		16	■	■	2190393 DHAA-G-Q11-16-B1-16		
16		20	■	■	2187838 DHAA-G-Q11-16-B1-20		
20		16	■	■	2190284 DHAA-G-Q11-20-B1-16		
20		20	■	■	2187713 DHAA-G-Q11-20-B1-20		
20		25	■	■	2185820 DHAA-G-Q11-20-B1-25		
25		16	■	■	1471634 DHAA-G-Q11-25-B1-16		
25		20	■	■	1722652 DHAA-G-Q11-25-B1-20		
25		25	■	■	1725707 DHAA-G-Q11-25-B1-25		
32		25	■	■	2186909 DHAA-G-Q11-32-B1-25		
32		35	■	■	2187316 DHAA-G-Q11-32-B1-35		
35, 40		35	■	■	2187606 DHAA-G-Q11-35/40-B1-35		

- Corrosion resistance class 2 according to Festo standard 940 070  
Components subject to moderate corrosion stress. Externally visible parts with primarily decorative surface requirements which are in direct contact with a normal industrial environment or media such as coolants or lubricating agents.
- Possible in combination with DRQD-...-E422 (flanged shaft with energy through-feed).
- Possible in combination with DRQD-...-E444 (flanged shaft with energy through-feed).


# Parallel grippers DHPS



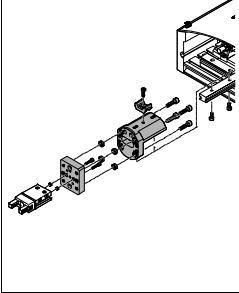
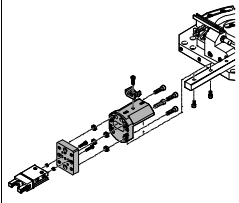
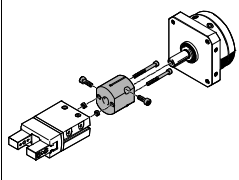
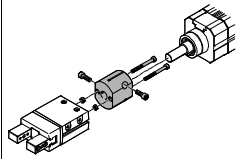
Accessories

FESTO

Adapter kit  
HAPG

Material:  
Wrought aluminium alloy  
Free of copper and PTFE  
RoHS-compliant

 Note  
The kit includes the individual mounting interface as well as the necessary mounting material.

Permissible drive/gripper combinations with adapter kit						Download CAD data → <a href="http://www.festo.com">www.festo.com</a>	
Combination	Drive Size	Gripper Size	Mounting option		Adapter kit		
					CRC <sup>1)</sup>	Part No.	Type
	HSP	DHPS			HAPG		
	12	6	■	–	2	192709	HAPG-60-S1
	16	6	■	–		540881	HAPG-70-B
	16	10	■	–		192706	HAPG-37-S1
	25	10	■	–		540882	HAPG-71-B
	25	16	■	–		192705	HAPG-36-S1
						540882	HAPG-71-B
						192705	HAPG-36-S1
						540883	HAPG-72-B
						193922	HAPG-37-S4
						540883	HAPG-72-B
	HSW	DHPS			HAPG		
	12, 16	6	■	–	2	192706	HAPG-37-S1
	12, 16	10	■	–		540882	HAPG-71-B
						192705	HAPG-36-S1
						540882	HAPG-71-B
	DSM:....FW	DHPS			HAPG		
	6, 8, 10	6	■	■	2	187568	HAPG-34
	DSM:...	DHPS			HAPG		
	12	10	■	■	2	163266	HAPG-17
	16	10	■	■		163267	HAPG-18
	16	16, 20	■	■		163268	HAPG-19
	25	16, 20	■	■		163269	HAPG-20
	25	25	■	■		163270	HAPG-21
	32	25	■	■		163271	HAPG-22
	DSL	DHPS			HAPG		
	16	10	■	■	2	163266	HAPG-17
	20	10	■	■		163267	HAPG-18
	20	16, 20	■	■		163268	HAPG-19
	25	16, 20	■	■		163269	HAPG-20
	25	25	■	■		163270	HAPG-21
	32	25	■	■		163271	HAPG-22

1) Corrosion resistance class 2 according to Festo standard 940 070  
Components subject to moderate corrosion stress. Externally visible parts with primarily decorative surface requirements which are in direct contact with a normal industrial environment or media such as coolants or lubricating agents.


# Parallel grippers DHPS



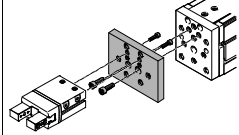
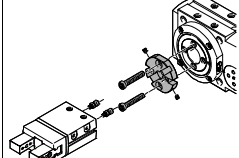
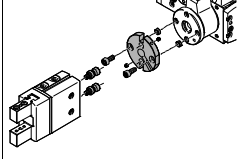
Accessories



**Adapter kit**  
HMSV, HAPG

Material:  
Wrought aluminium alloy  
Free of copper and PTFE  
RoHS-compliant

 Note  
The kit includes the individual mounting interface as well as the necessary mounting material.

Permissible drive/gripper combinations with adapter kit						Download CAD data → <a href="http://www.festo.com">www.festo.com</a>	
Combination	Drive Size	Gripper Size	Mounting option		Adapter kit		
					CRC <sup>1)</sup>	Part No.	Type
<b>EGSL/DHPS</b>	<b>EGSL</b>	<b>DHPS</b>			<b>HMSV</b>		
	35	6	■	■	2	548783	HMSV-53
	35	10	■	■		1088262	HMSV-70
			■	■		548784	HMSV-54
	45, 55	16	■	■		1088262	HMSV-70
75	20, 25	■	■	548785	HMSV-55		
					548786	HMSV-56	
<b>ERMB/DHPS</b>	<b>ERMB</b>	<b>DHPS</b>			<b>HAPG</b>		
	20	16, 20	■	■	2	184479	HAPG-SD2-3
	25	16, 20	■	■		184482	HAPG-SD2-6
	20	25	■	■		184480	HAPG-SD2-4
	25	25	■	■		184483	HAPG-SD2-7
	32	25	■	■		184485	HAPG-SD2-9
	32	35	■	■		184486	HAPG-SD2-10
<b>EHMB/DHPS</b>	<b>EHMB</b>	<b>DHPS</b>			<b>HAPG</b>		
	20	25	■	■	2	184485	HAPG-SD2-9
	20	35	■	■		184486	HAPG-SD2-10
	25, 32	35	■	■		526027	HAPG-SD2-21

1) Corrosion resistance class 2 according to Festo standard 940 070  
Components subject to moderate corrosion stress. Externally visible parts with primarily decorative surface requirements which are in direct contact with a normal industrial environment or media such as coolants or lubricating agents.

# Parallel grippers DHPS

Accessories

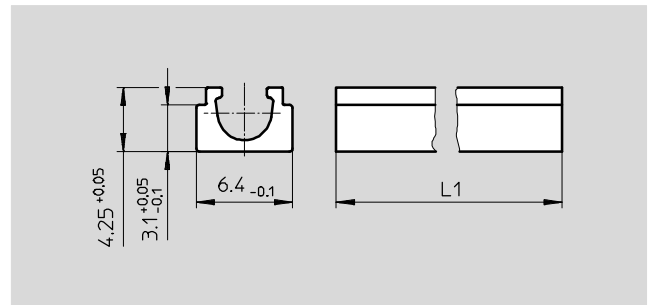
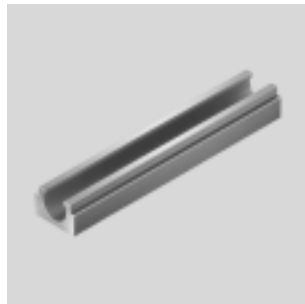


## Sensor rail HGP-SL

can be glued into place

Material:

Wrought aluminium alloy



Dimensions and ordering data					
For size [mm]	L1	Weight [g]	Part No.	Type	
10	35	1.4	535582	HGP-SL-10-10	
16	38	1.5	535583	HGP-SL-10-16	
20	50	2.0	535584	HGP-SL-10-20	
25	58	2.3	535585	HGP-SL-10-25	
35	65	2.6	535586	HGP-SL-10-35	

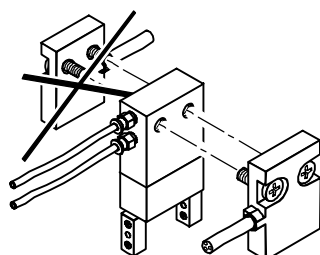
Ordering data						
	For size [mm]	Description	Weight [g]	Part No.	Type	PU <sup>1)</sup>
Centring sleeve ZBH			Technical data → Internet: zbh			
	10	For centring the gripper fingers on the gripper jaws	1	189652	ZBH-5	10
	16, 20		1	186717	ZBH-7	
	25, 35		1	150927	ZBH-9	
	6, 10	For centring the gripper when mounting	1	189652	ZBH-5	
	16, 20		1	186717	ZBH-7	
	25		1	150927	ZBH-9	
	35		1	189653	ZBH-12	

1) Packaging unit

Ordering data					
Type	For size	Weight [g]	Part No.	Type	
Position sensor SMH-S1					
Technical data → Internet: smh-s1					
	6	20	175710	SMH-S1-HGP06	

## Installation instructions for position sensor SMH-S1

To guarantee the functionality of the position sensor, the outlet for the cable and the compressed air tubing must be facing the same direction during installation.



# Parallel grippers DHPS

Accessories

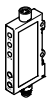

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## Signal converter/evaluation unit for position sensor SMH-S1





Signal converter SVE4      Evaluation unit SMH-AE1

- Converts analogue signals into switching points
- Switching function freely programmable with teach-in
- Threshold value, hysteresis or window comparator
- Converts analogue signals into switching points
- With 3 potentiometers for setting 3 switching points

### Ordering data

Type	For size	Input connection	Output connection	Switching output	Weight [g]	Part No.	Type
Signal converter SVE4						Technical data → Internet: sve4	
	6	Socket M8x1, 4-pin	Plug M8x1, 4-pin	2x PNP	19	544216	SVE4-HS-R-HM8-2P-M8
				2x NPN		544219	SVE4-HS-R-HM8-2N-M8
Evaluation unit SMH-AE1						Technical data → Internet: smh-ae	
	6	Socket M8x1, 4-pin	Plug M12x1, 5-pin	3x PNP	170	175708	SMH-AE1-PS3-M12
				3x NPN		175709	SMH-AE1-NS3-M12

### Ordering data – Connecting cables


	Electrical connection, left	Electrical connection, right	Cable length [m]	Part No.	Type
Technical data → Internet: nebu					
Connection between position sensor and signal converter/evaluation unit					
	Straight socket, M8x1, 4-pin	Straight plug, M8x1, 4-pin	2.5	554035	NEBU-M8G4-K-2.5-M8G4
Connection between evaluation unit and controller					
	Straight socket, M12x1, 5-pin	Cable, open end, 5-wire	2.5	541330	NEBU-M12G5-K-2.5-LE5
			5	541331	NEBU-M12G5-K-5-LE5
Connection between signal converter and controller					
	Straight socket, M8x1, 4-pin	Cable, open end, 4-wire	2.5	541342	NEBU-M8G4-K-2.5-LE4
			5	541343	NEBU-M8G4-K-5-LE4
	Angled socket, M8x1, 4-pin	Cable, open end, 4-wire	2.5	541344	NEBU-M8W4-K-2.5-LE4
			5	541345	NEBU-M8W4-K-5-LE4

# Parallel grippers DHPS


Accessories

FESTO



## Proximity sensor for size 10 ... 35

Ordering data – Proximity sensors for T-slot, magneto-resistive						Technical data → Internet: smt	
Type of mounting	Electrical connection, connection direction	Switching output	Cable length [m]	Part No.	Type		
N/O contact							
	Insertable in the slot lengthwise	Cable, 3-wire, lateral	PNP	2.5	547859	SMT-8G-PS-24V-E-2,5Q-OE	
		Plug M8x1, 3-pin, lateral		0.3	547860	SMT-8G-PS-24V-E-0,3Q-M8D	

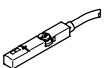
## Proximity sensor for size 10 ... 35, with sensor rail HGP-SL10-...


Ordering data – Proximity sensors for C-slot, magneto-resistive						Technical data → Internet: smt	
Type of mounting	Electrical connection, connection direction	Switching output	Cable length [m]	Part No.	Type		
N/O contact							
	Insertable in the slot lengthwise	Cable, 3-wire, lateral	PNP	2.5	547862	SMT-10G-PS-24V-E-2,5Q-OE	
		Plug M8x1, 3-pin, lateral		0.3	547863	SMT-10G-PS-24V-E-0,3Q-M8D	

## Ordering data – Connecting cables

Ordering data – Connecting cables				Technical data → Internet: nebu	
Electrical connection, left	Electrical connection, right	Cable length [m]	Part No.	Type	
	Straight socket, M8x1, 3-pin	Cable, open end, 3-wire	2.5	541333	NEBU-M8G3-K-2.5-LE3
			5	541334	NEBU-M8G3-K-5-LE3
	Angled socket, M8x1, 3-pin	Cable, open end, 3-wire	2.5	541338	NEBU-M8W3-K-2.5-LE3
			5	541341	NEBU-M8W3-K-5-LE3

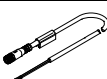

## Proximity sensor for size 10 ... 35

Ordering data – Position transmitters for T-slot						Technical data → Internet: smat	
Type of mounting	Electrical connection, connection direction	Analogue output [V]	Cable length [m]	Part No.	Type		
	Insertable in the slot from above	Plug M8x1, 4-pin, in-line	0 ... 10	0.3	553744	SMAT-8M-U-E-0,3-M8D	

 Note

**Mode of operation:**  
The position transmitter continuously senses the position of the piston. It has an analogue output with an output signal in proportion to the piston position.

## Ordering data – Connecting cables

Ordering data – Connecting cables				Technical data → Internet: nebu	
Electrical connection, left	Electrical connection, right	Cable length [m]	Part No.	Type	
	Straight socket, M8x1, 4-pin	Cable, open end, 4-wire	2.5	541342	NEBU-M8G4-K-2.5-LE4
			5	541343	NEBU-M8G4-K-5-LE4
	Angled socket, M8x1, 4-pin	Cable, open end, 4-wire	2.5	541344	NEBU-M8W4-K-2.5-LE4
			5	541345	NEBU-M8W4-K-5-LE4